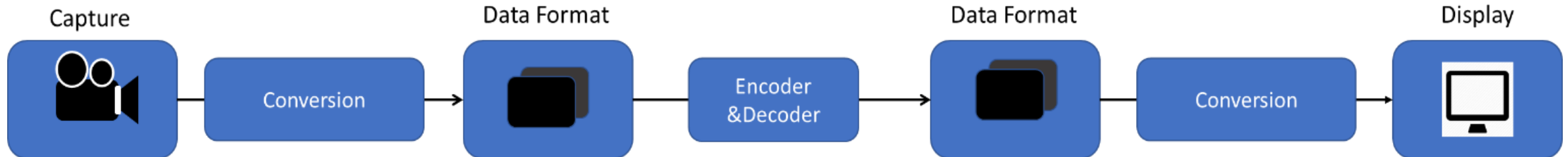


# How to achieve dense light field video compression?

**Mehrdad Teratani** (Associate Professor, Nagoya University)

Xin Jin (Graduate School at Shenzhen, Tsinghua University)



# Dense light field

## Muti-cam (multiview)



2004-2008

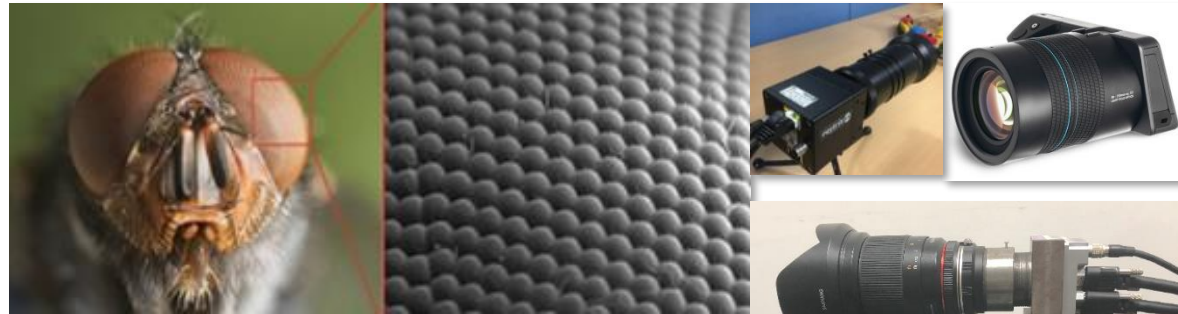
NAGOYA  
UNIVERSITY



2012 @ Osaka



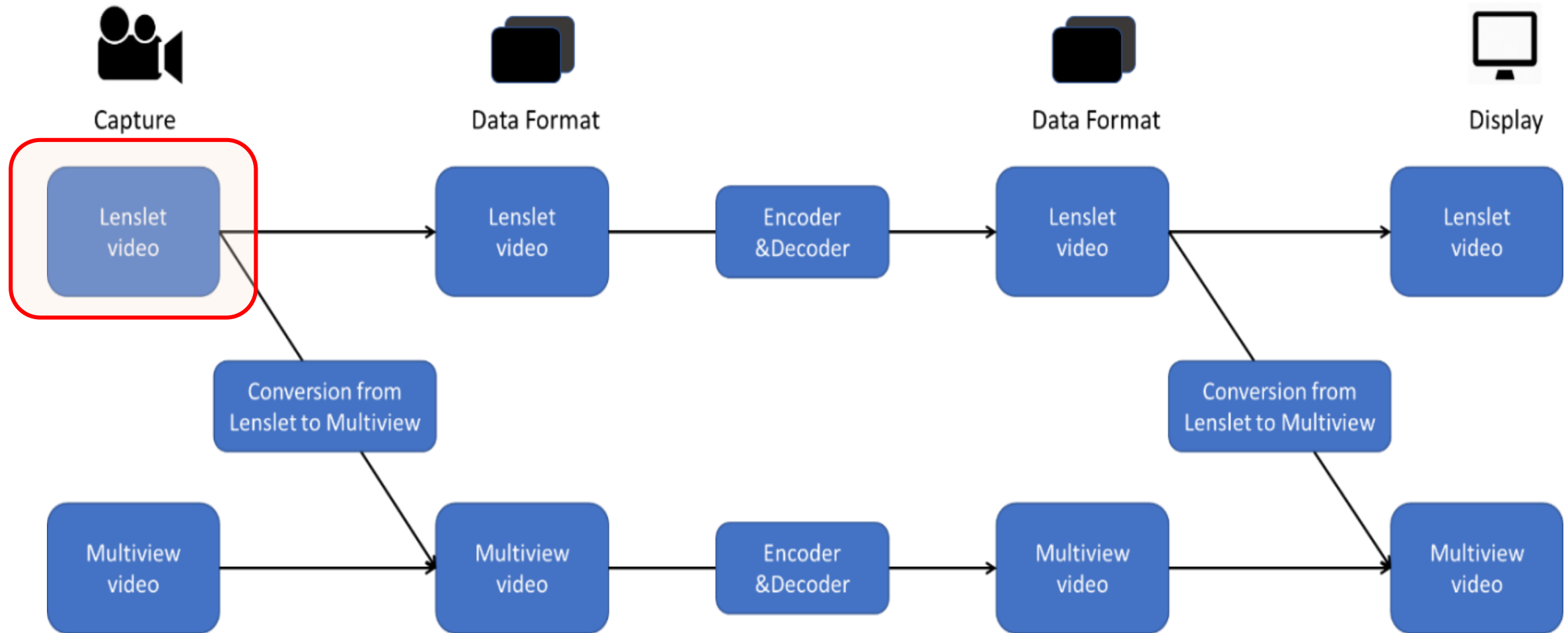
## Plenoptic (lenslet)



清华大学  
Tsinghua University

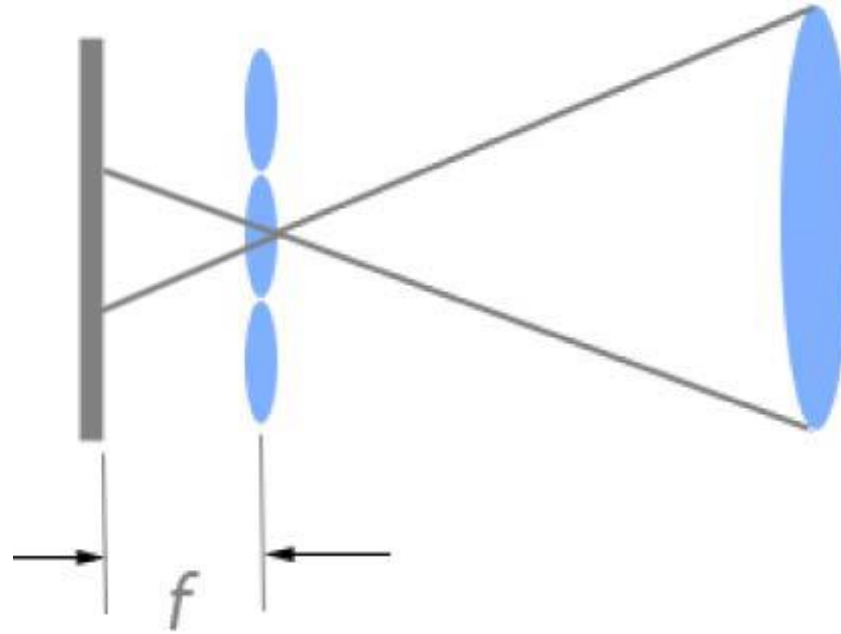
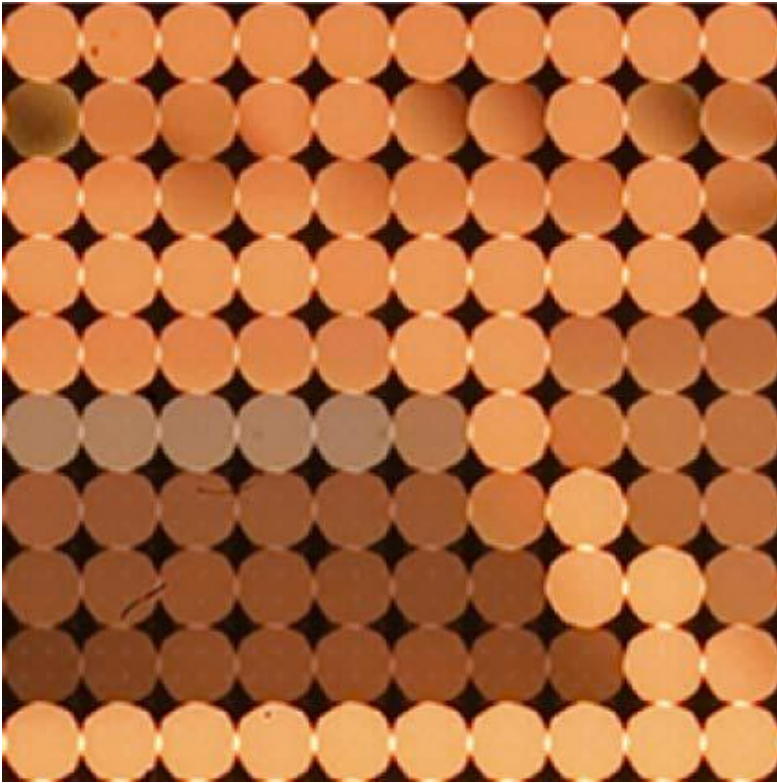


# End-to-end system for dense light field



# Plenoptic Camera type 1.0

Plenoptic 1.0 (e.g., Lytro)



"Lytro," <https://www.lytro.jp/>.

- Spatial resolution = number of microlens.
- Completely defocused relative to main lens image.



# GSST Plenoptic 1.0 Lenslet Data



**M44684: “Toys”**



**M44684: “Trees”**



**M46258: “Teapots”**



**M46258: “Mini-garden”**



Lenslet Video Data

Resolution: 8656×6075  
Color: 24 bits, PNG  
Frame rate: 30 fps

Lenslet Video Data

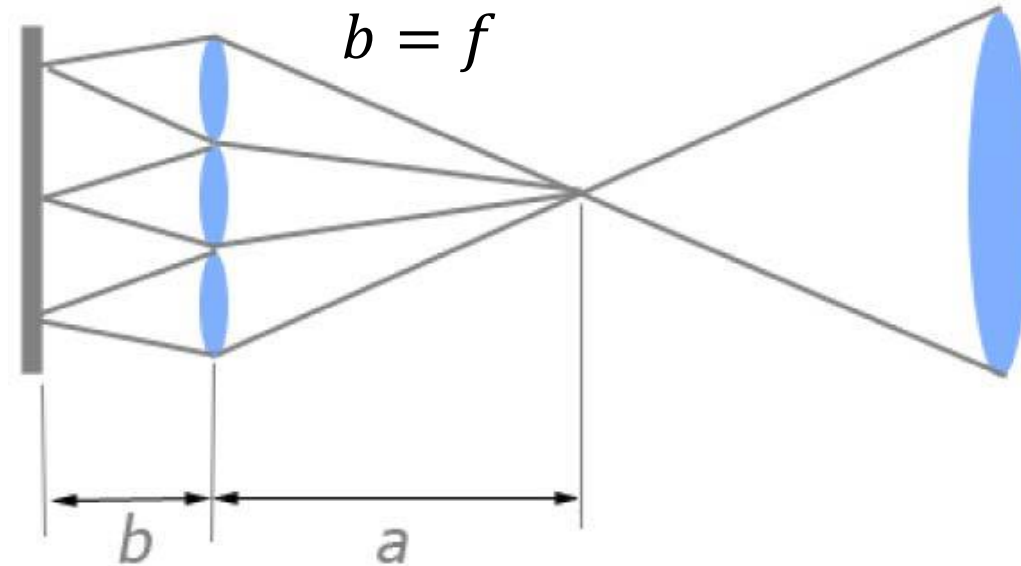
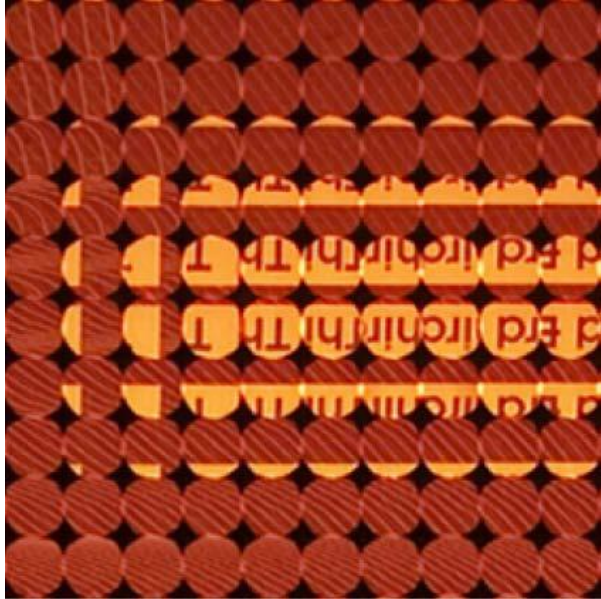
Resolution: 8654×6074  
Color: 24 bits, PNG  
Frame rate: 30 fps

# Plenoptic Camera 2.0



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## Single-Focused Plenoptic Camera



- resolution independent of microlenses
- spatial-angular resolution = free tradeoff point.
- Exactly focused on the main lens image.



Designed and made by  
Tsinghua University



# GSST Plenoptic 2.0 Lenslet data



**M46259: “Boys”**



**M46259: “Experimenting”**



**M49007: “cars”**



## Colored Lenslet Video Data

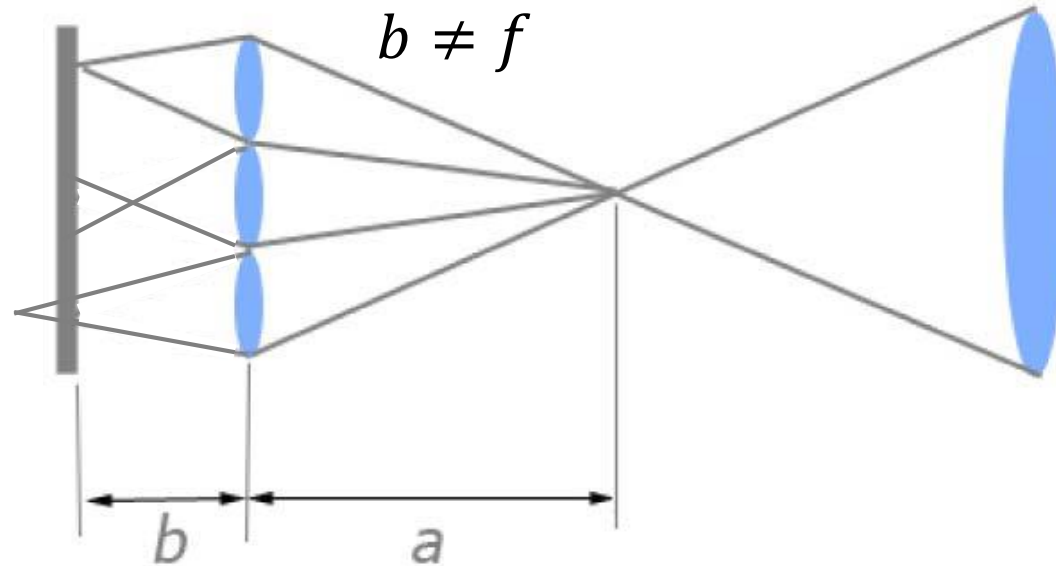
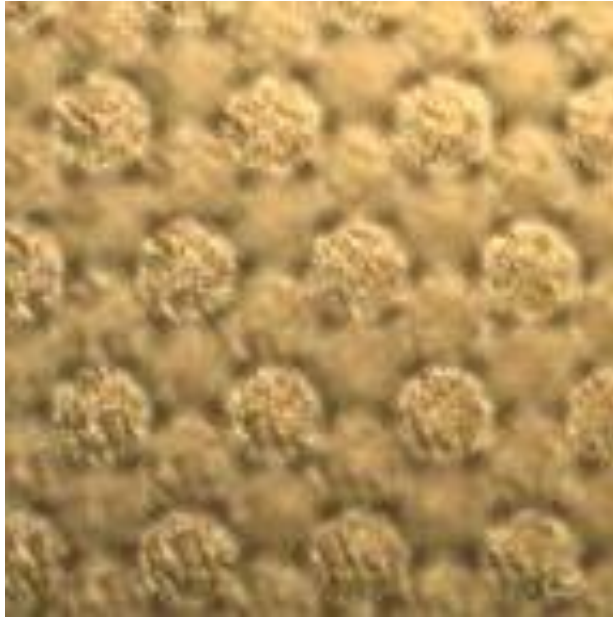
Resolution: 4088×3068  
Color: 24 bits, BMP  
Frame rate: 30 fps  
Number of frames: 300

## Multiview Video Data

Resolution of each view: 926×672  
Views: 5×5  
Number of frames: 300

# Plenoptic Camera 2.0

## Multi-Focused Plenoptic Camera



"Raytrix," <https://www.raytrix.de/>.

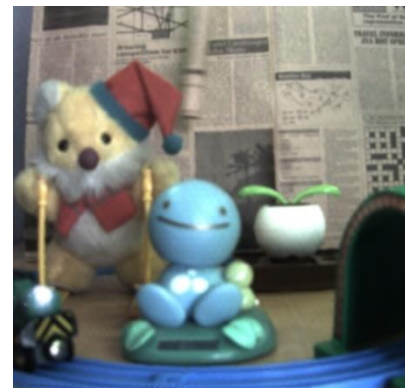
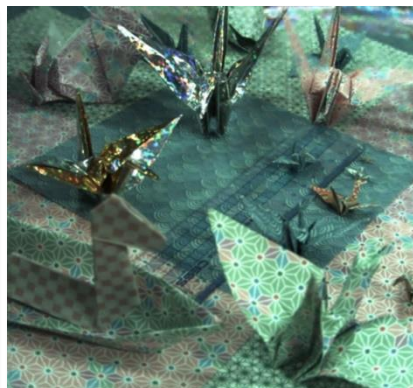
- Flexible (3 kind of ML)
- resolution independent of microlenses
- spatial-angular resolution = free tradeoff point.



# Nagoya University Lenslet data

## Plenoptic 2.0

Center viewpoint

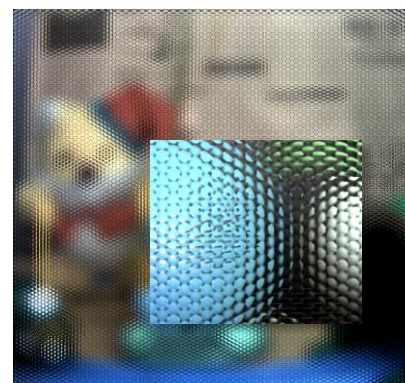
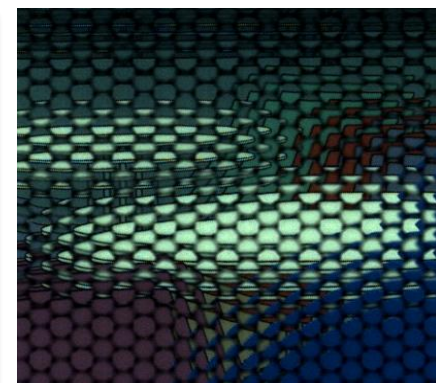
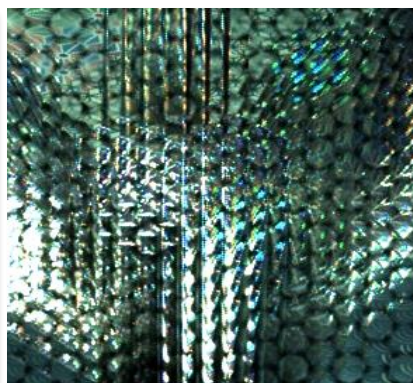
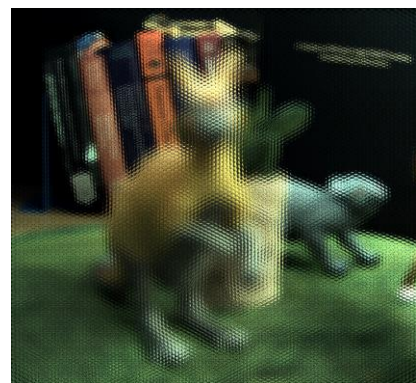


### Colored Lenslet Video

Resolution: **2048x2048 pixels**  
 Color: 24 bits PNG, and YUV420  
 Frame rate: 30 fps  
 Number of frames: 300-400  
 Camera parameters (SDK output)

Raytrix R5-C- GigE-F2.4 (color)  
 Main Lens: LMVZ166HC (Kowa)

Lenslet



### NagoyaFujita

Fixed Camera  
 Horizontal view  
 M47642, M49670

### NagoyaOrigami

Fixed Camera  
 Top view  
 M47642, M49670

### NagoyaDataLeading

Camera on turn table  
 Horizontal view  
 M47642, M49670

### Tunnel Train 2

Fixed Camera  
 Horizontal view  
 M41787





# INRIA Lenslet data Plenoptic 2.0



ULB

## Colored Lenslet Video

Resolution: **3840 × 2160 pixels**  
Color: 24 bits, PNG  
Frame rate: 30 fps  
Number of frames: 300  
Camera parameters (SDK output)

Raytrix R8



"Raytrix," <https://www.raytrix.de/>.



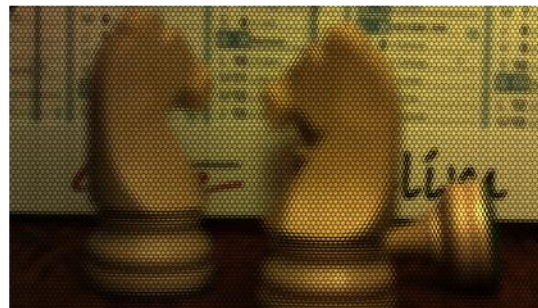
Boxer-IrishMan-Gladiator



Chess-Pieces

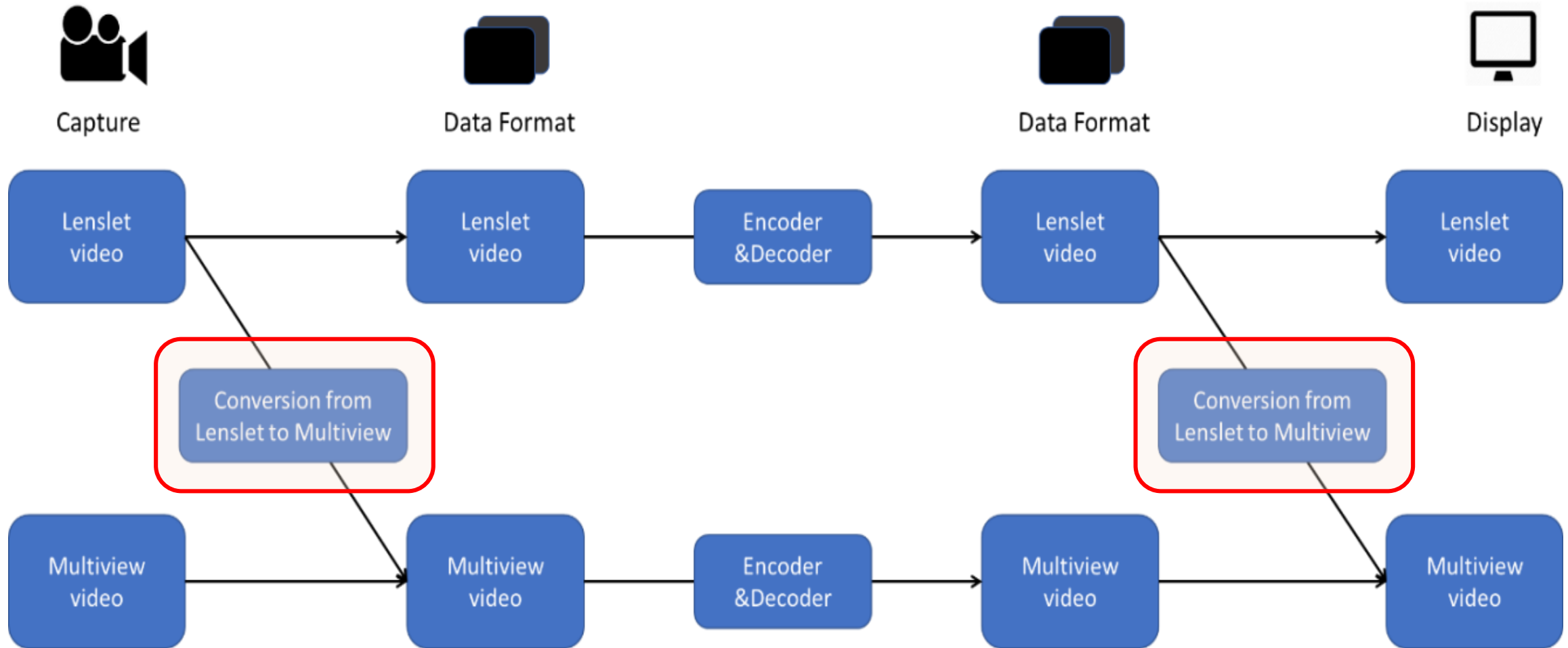


ChessPieces-MovingCamera



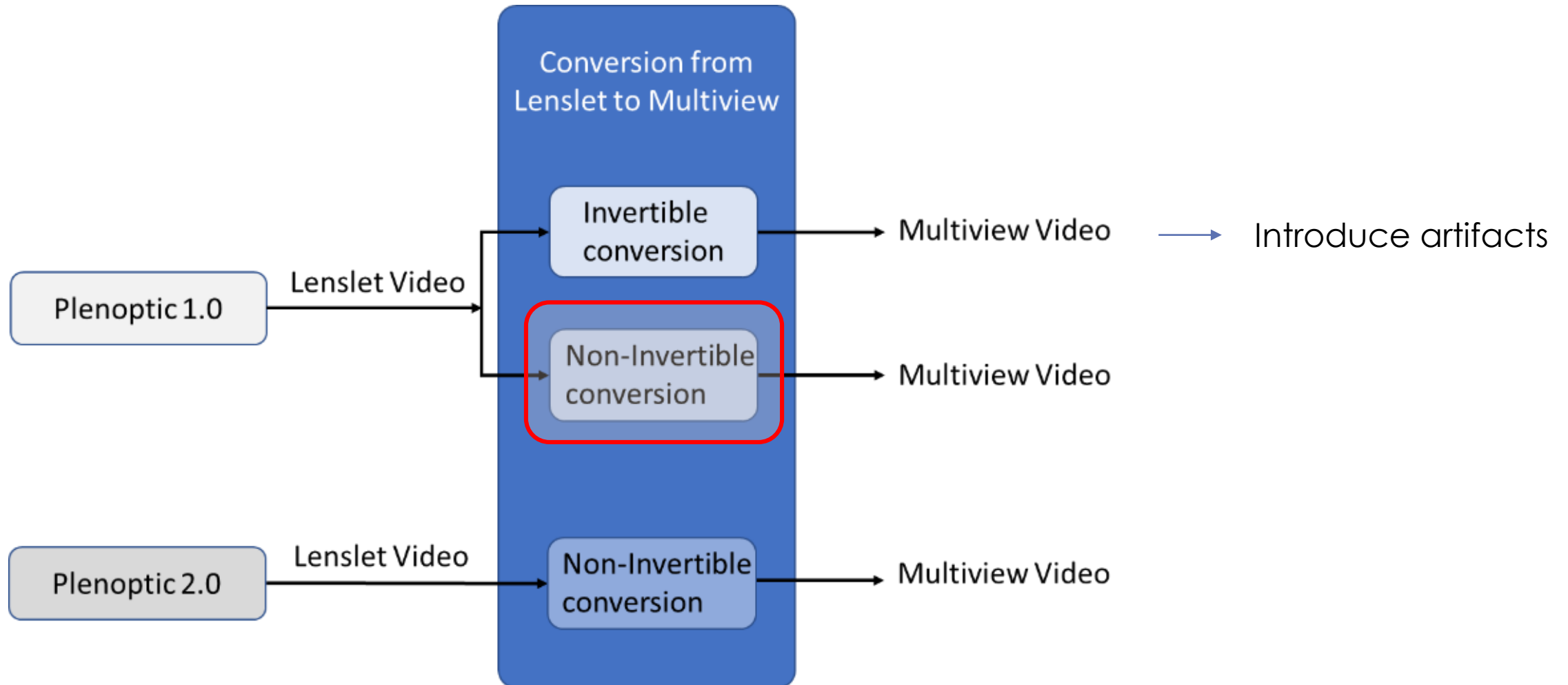
m42468

# End-to-end system for dense light field

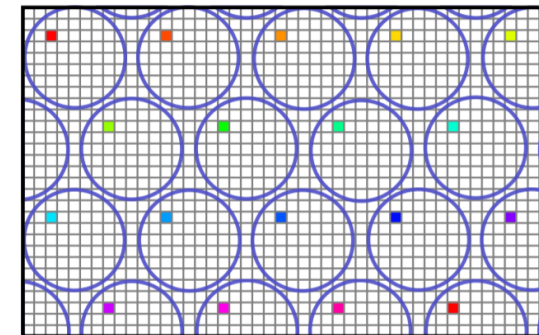
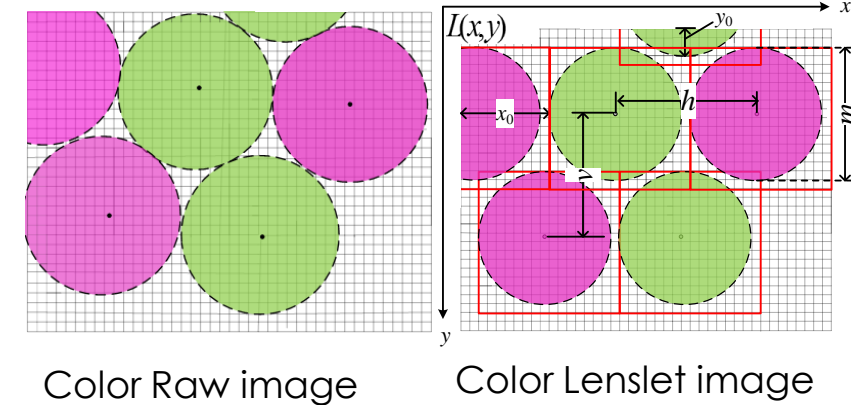
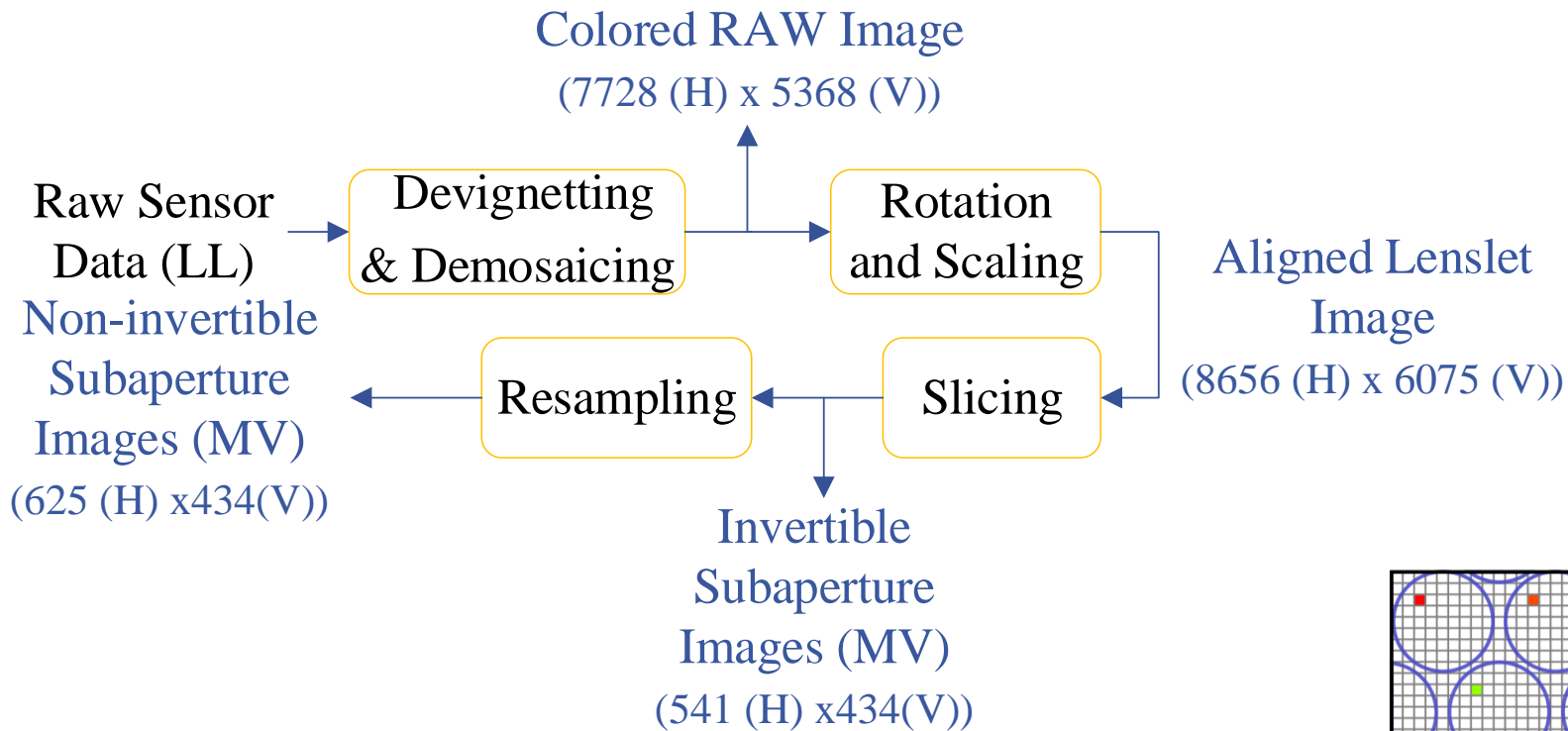




# Conversion from Lenslet to Multiview

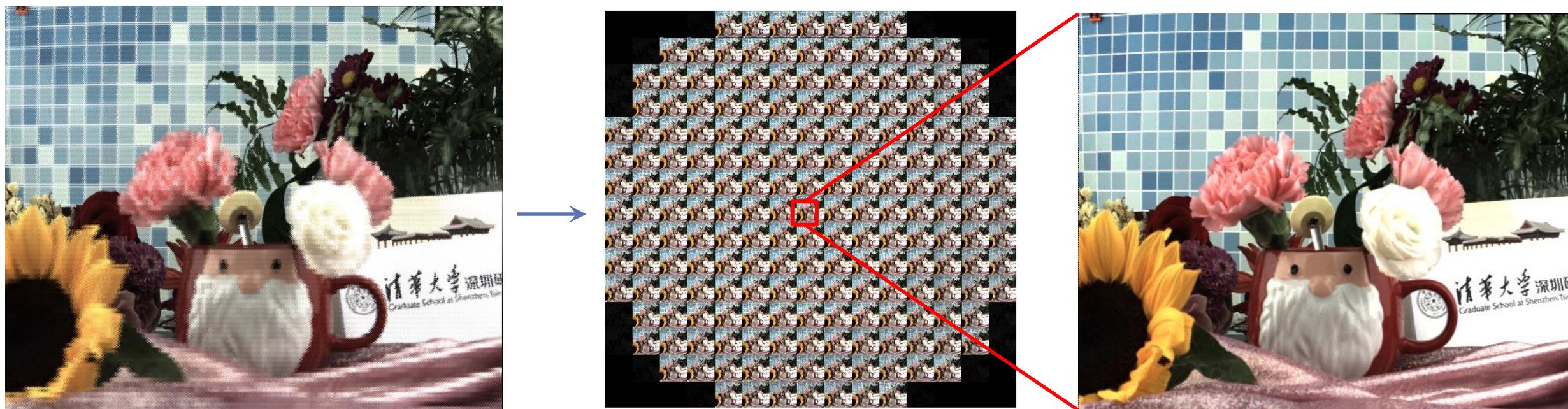


# Plenoptic 1.0 Data Conversion Tool

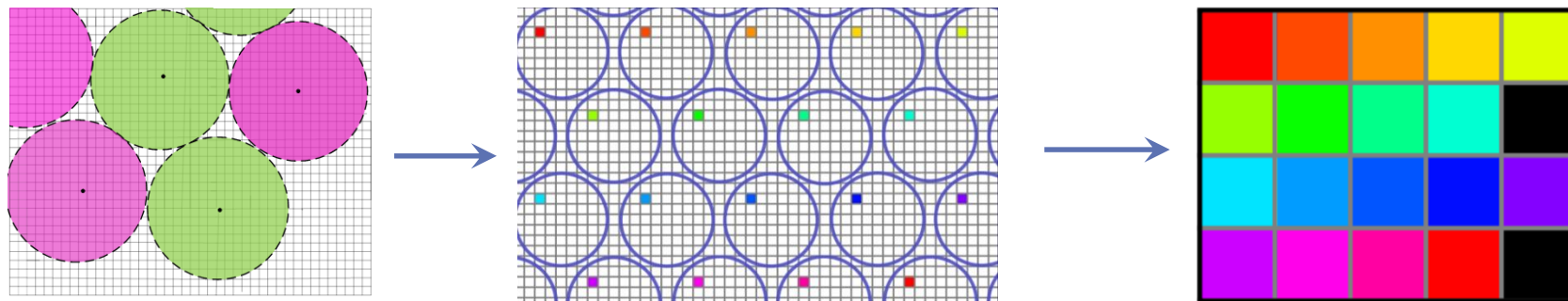


P. David et al. MMSP2017

# Plenoptic 1.0 Data Conversion Tool

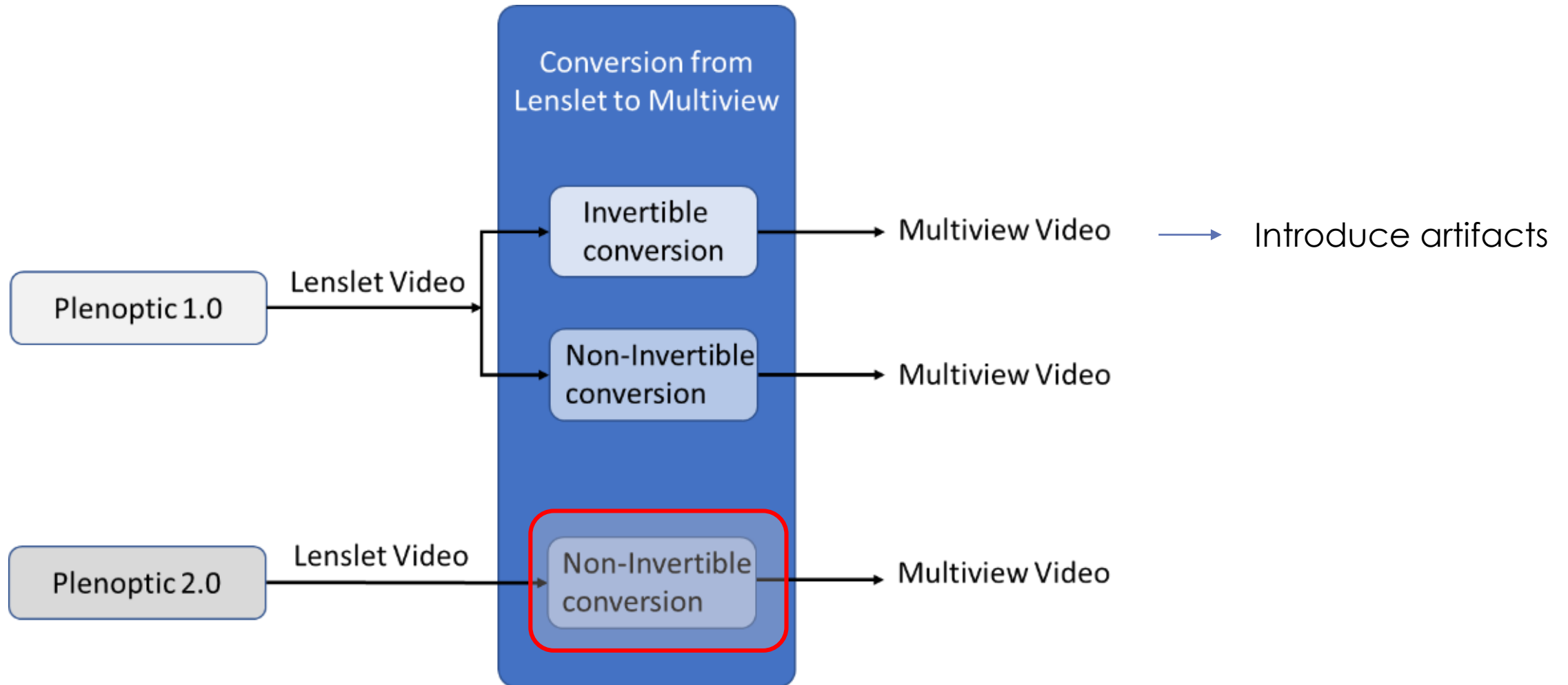


M44684: New Test Sequences "Toys" and "Trees" Captured by a Light Field Camera @MPEG,Macao

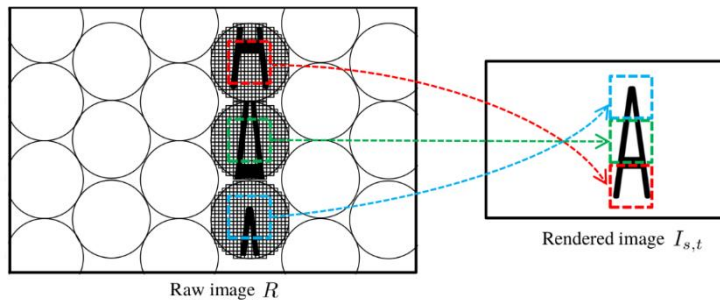
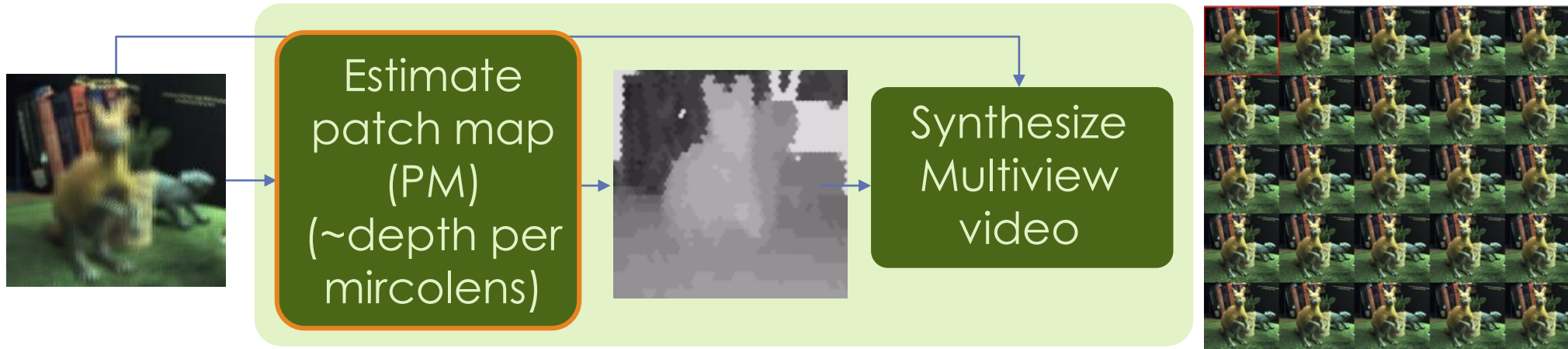




# Conversion from Lenslet to Multiview



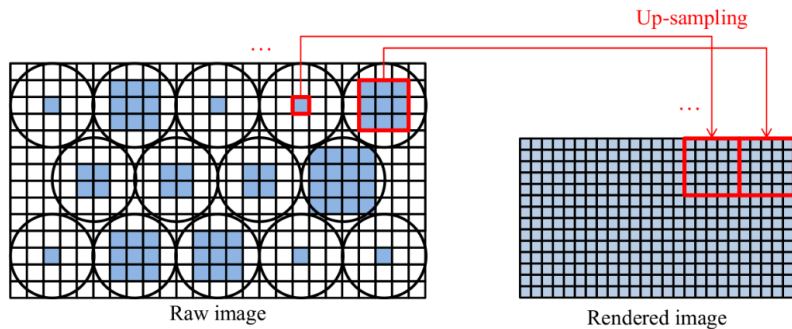
# Reference Lenslet content Convertor



$$K(i, j) = \arg \min E_k(i, j)$$

$$E'_k(i, j) = \sum_{s \in \mathcal{S}} \sum_{t \in \mathcal{T}} \sum_{(u, v) \in b(i, j)} \nabla^2 I_k^{(s, t)}(u, v)$$

$K(i, j)$  is the suitable patch size for the  $(i, j)$ -th microlens,  $b(i, j)$  contains the pixel indices of patch border at the  $(i, j)$ -th microlens.  $(s, t)$  and  $(u, v)$  are view and pixel coordinates.

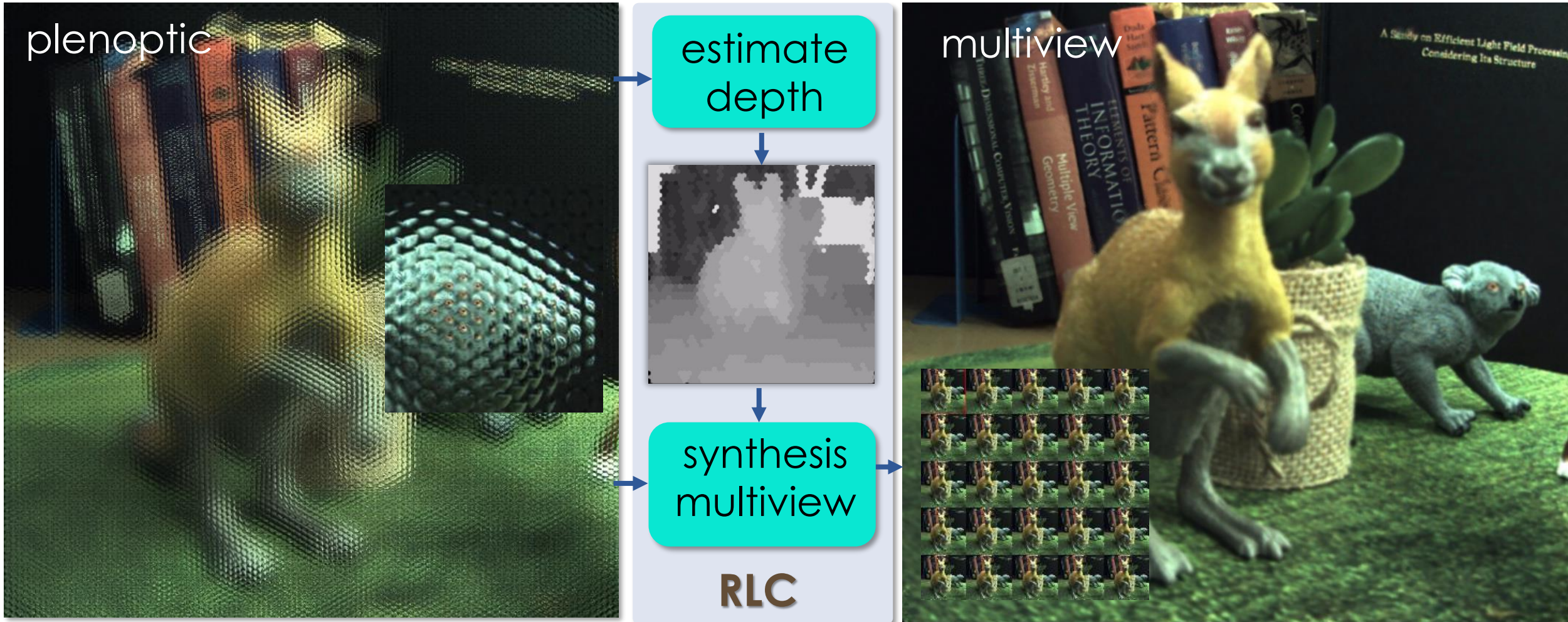


**Reference Lenslet content Convertor (RLC)**

MPEG (2017 - 2019), IC3D2018



# RLC: Plenoptic 2.0 to Multiview

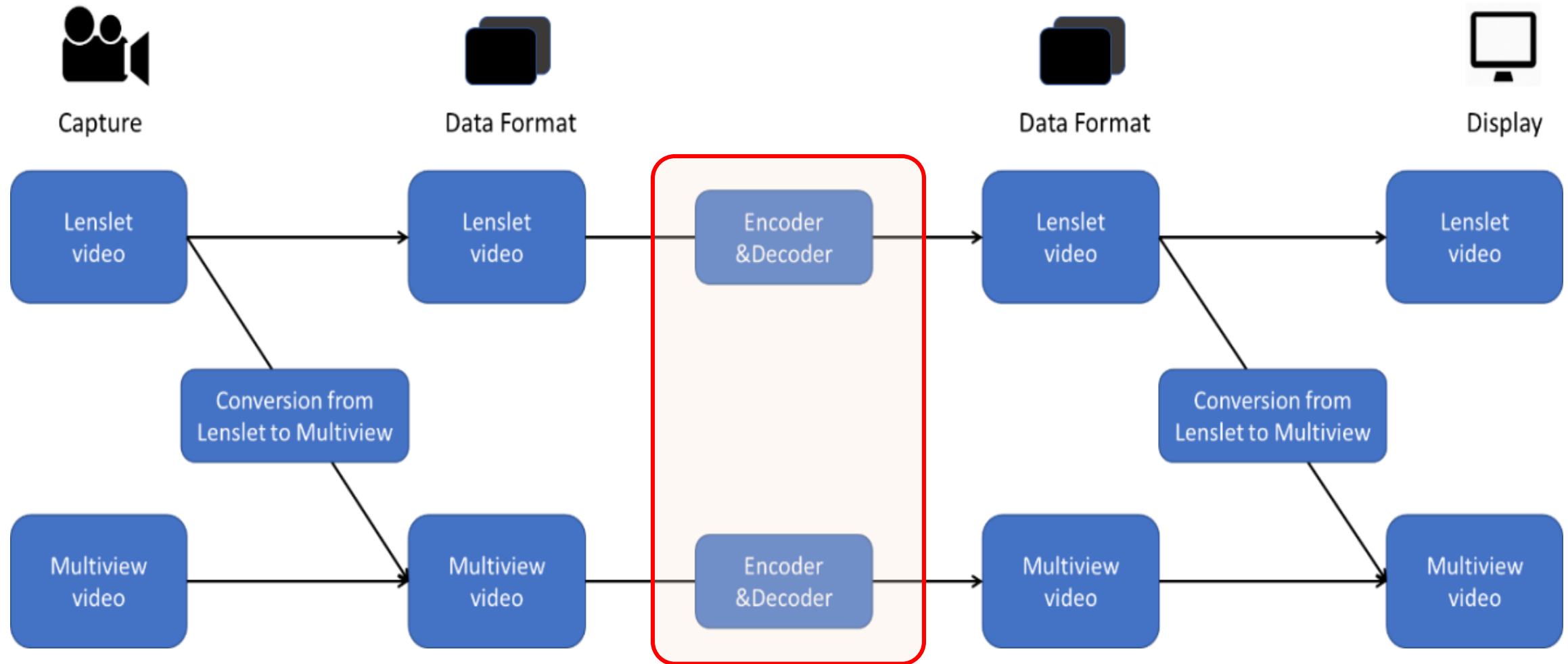


**Reference Lenslet content Converter (RLC)**

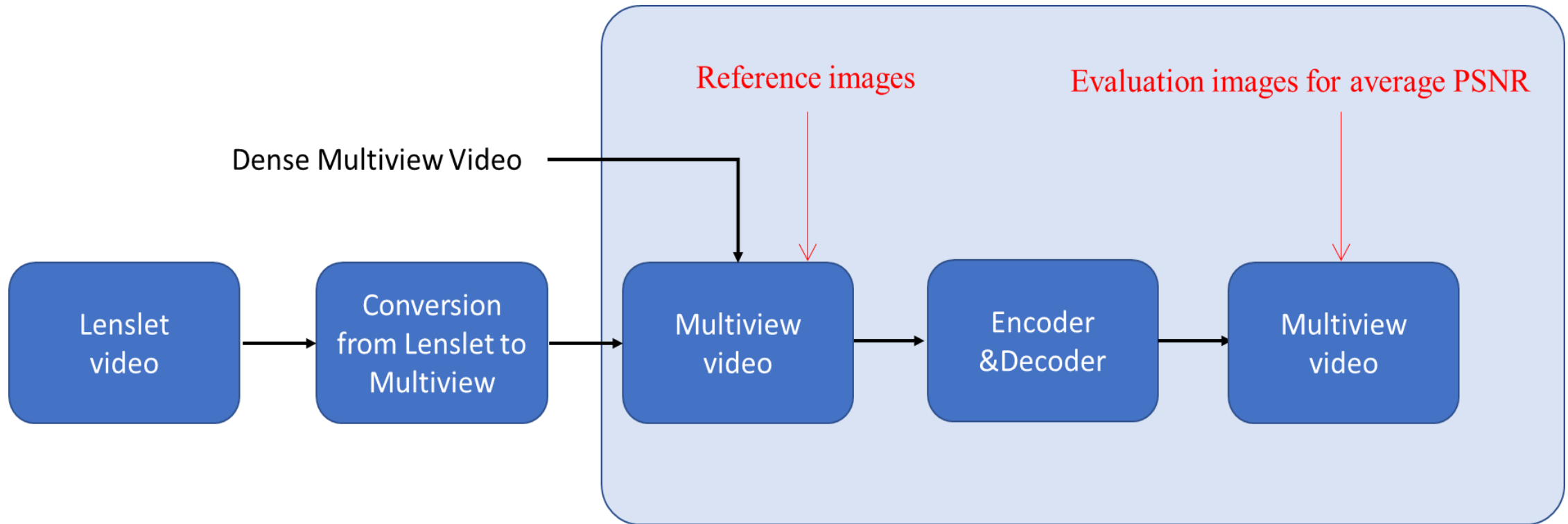
MPEG (2017 - 2019), IC3D2018



# End-to-end system for dense light field

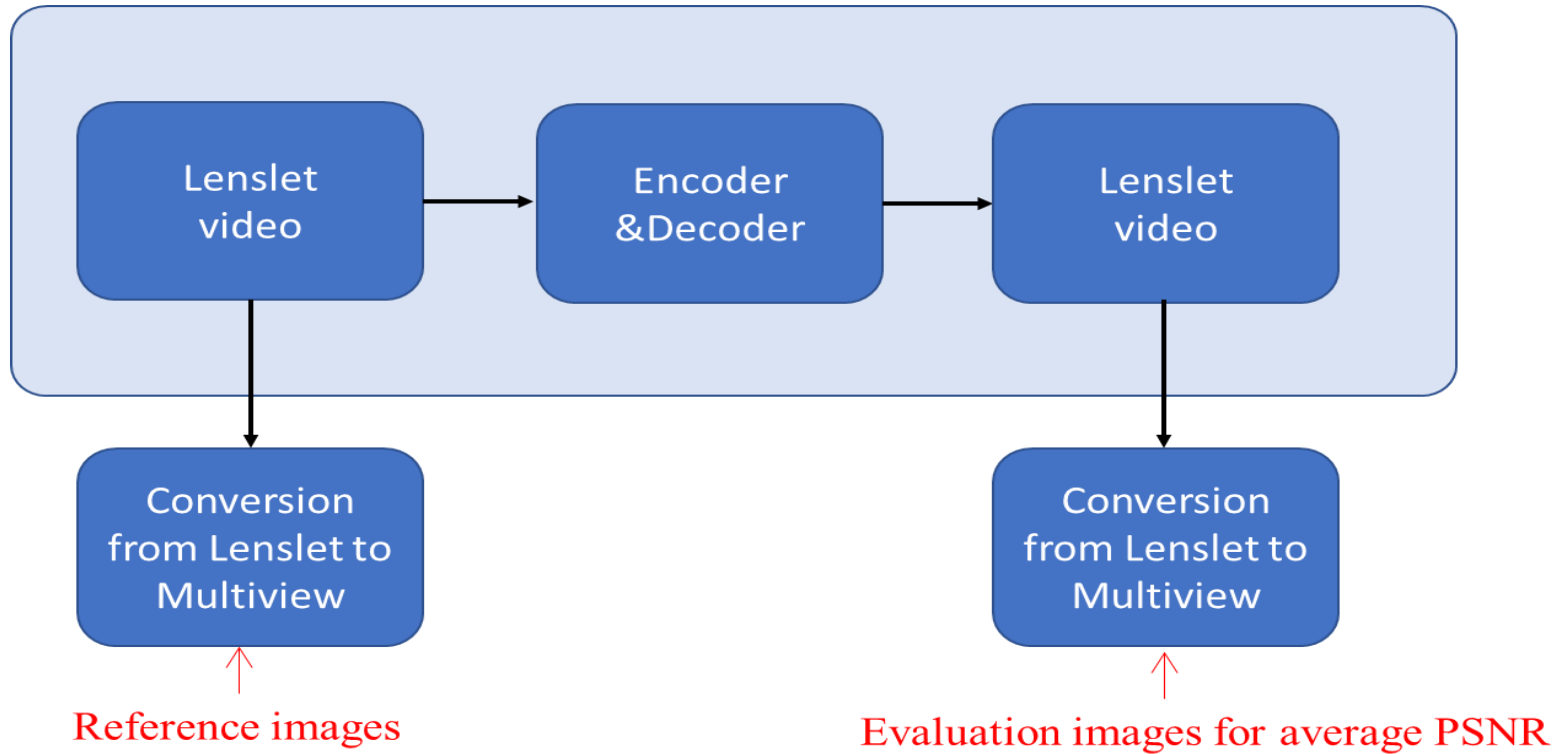


# EE\_MV: Multiview>Compression>Multiview



Plenoptic 1.0	Plenotic 2.0
HTM16.2	HM-16.9_SCM_8.0

# EE\_LL: Lenslet>Compression>Lenslet

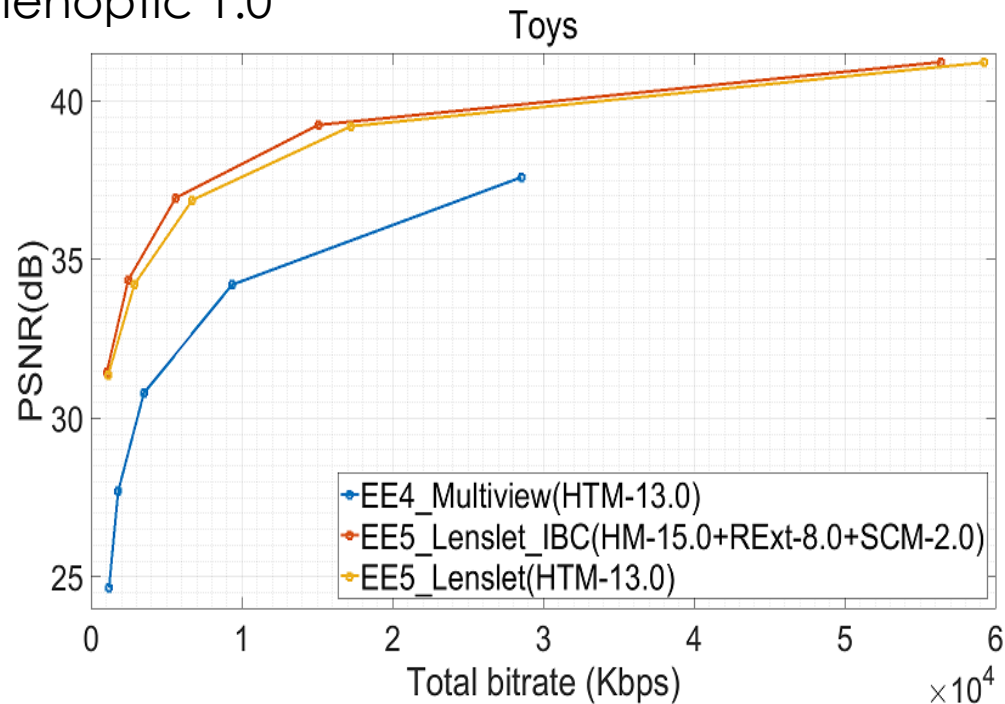


Plenoptic 1.0	Plenoptic 2.0
HTM16.2	HM-16.9_SCM_8.0

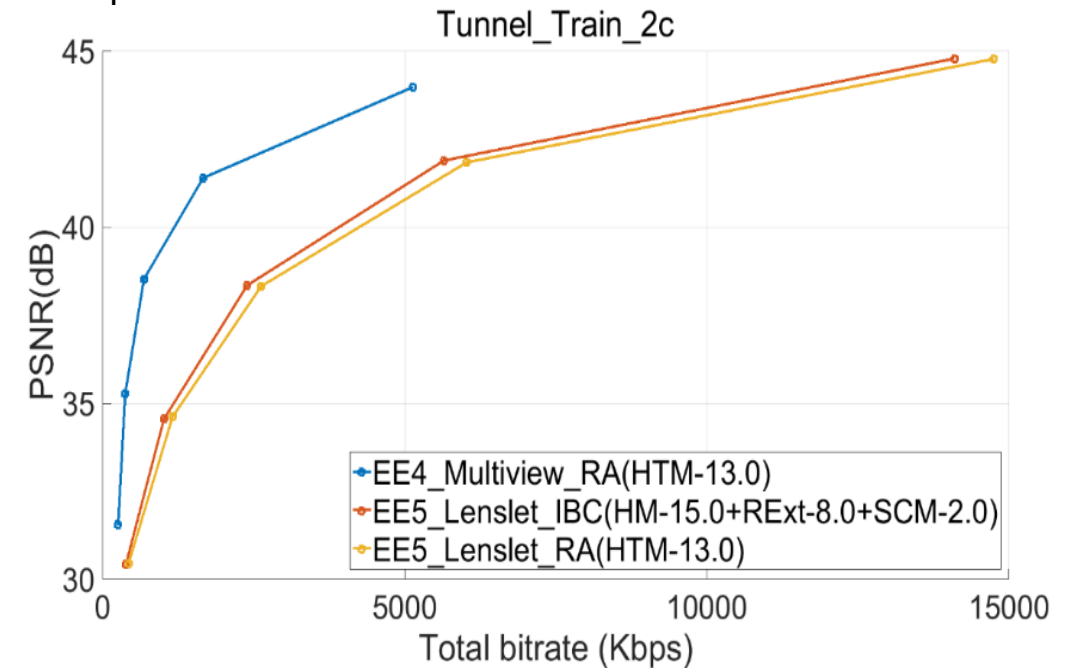


# Compression of plenoptic 1.0 vs plenoptic 2.0

Plenoptic 1.0



Plenoptic 2.0



Plenoptic 1.0	Plenoptic 2.0
EE_LL > EE_MV	EE_MV > EE_LL



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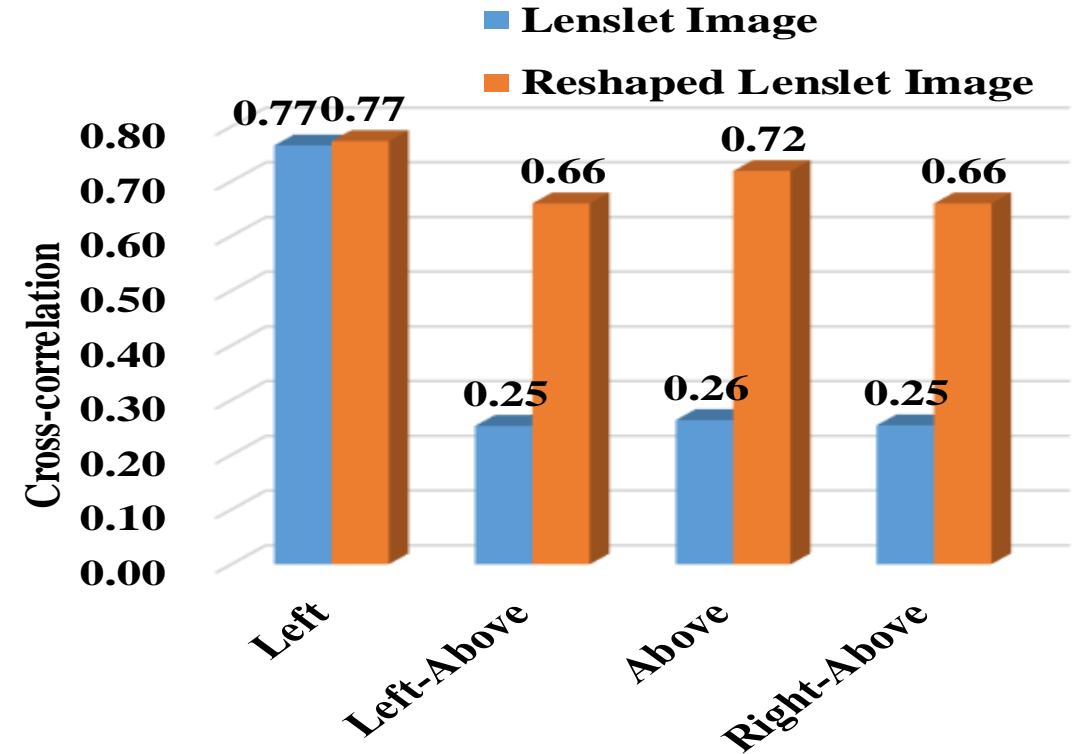
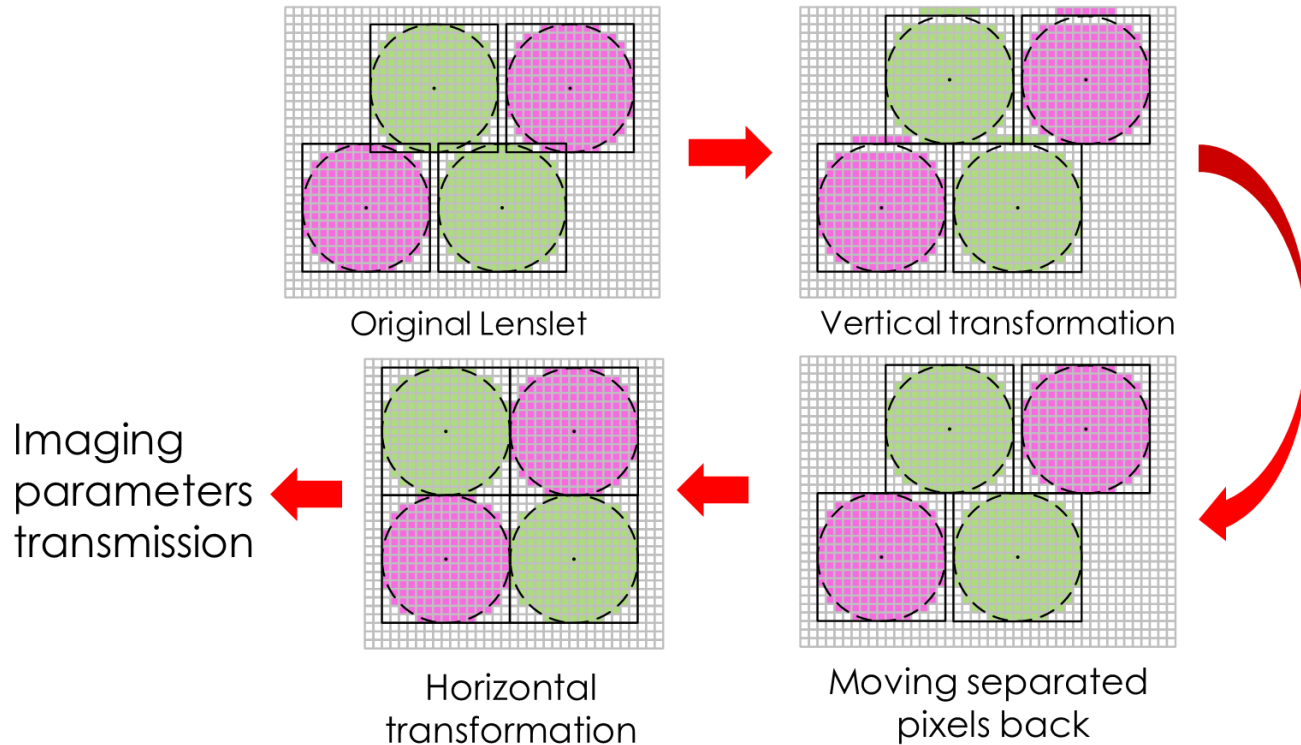
NAGOYA  
UNIVERSITY

# New coding tools for EE\_LL



- M44685: Imaging Reshaping (IR)
- M46261: Boundary matching based prediction

# Imaging Reshaping (IR)



X. Jin, H. Han, and Q. Dai. "Image Reshaping for Efficient Compression of Plenoptic Content." IEEE Journal of Selected Topics in Signal Processing, 11(7): 1173-1186, 2017

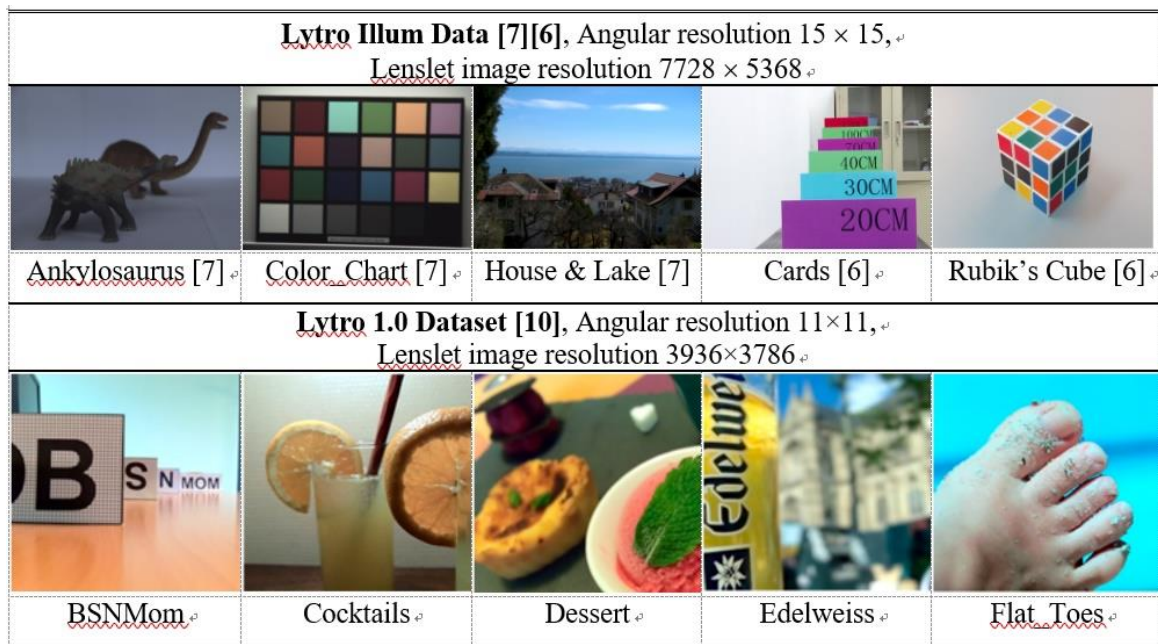


# Imaging Reshaping



## Test conditions:

- Reference Software: HM-16.9SCM8.0
- Profile: HEVC Format Range Extension(RExt)
- All Intra Main
- Input Color Format: YUV4:4:4
- QP: 26, 32, 38, 44
- Evaluation: light field performance BD-bitrate

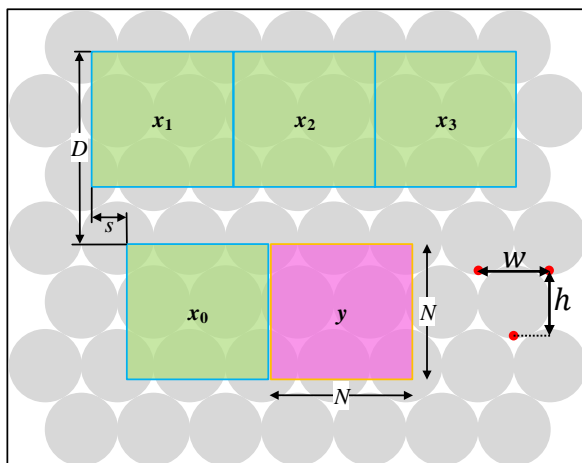


Datasets	Image Name	IR vs. HEVC
Lytro Illum	Ankylosaurus	-30.0%
	Color_Chart	-15.6%
	House & Lake	-34.0%
	Cards	-8.6%
	Rubik's Cube	-13.9%
Lytro 1.0	BSNMom	-23.1%
	Cocktails	-19.8%
	Dessert	-13.6%
	Edelweiss	-4.1%
	Flat_Toos	-20.6%
Average		-18.3%

# Boundary matching based prediction

high correlations among the neighboring macropixels  $\longrightarrow$  collocated blocks are used to predict the current PU

PU size is  $32 \times 32$  or  $64 \times 64$

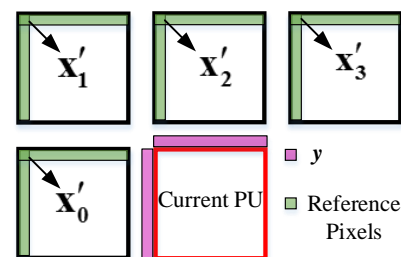


Current PU  
Reference Blocks

$$D = \left\lceil \frac{N}{h} \right\rceil \times h$$

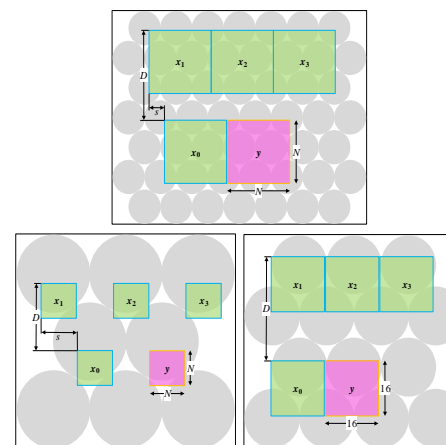
$$S = \begin{cases} \frac{w}{2}, & \left\lceil \frac{N}{h} \right\rceil \in O \\ 0, & \left\lceil \frac{N}{h} \right\rceil \in E \end{cases}$$

Weights determination



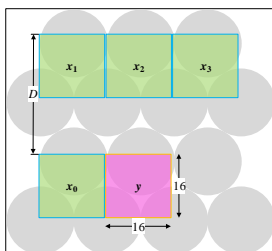
$$\begin{aligned} &\text{minimize } \|Xw - y\|_2^2 \\ &\text{subject to } \mathbf{1}^T \mathbf{w} = \mathbf{1} \\ &\quad \mathbf{w} \geq \mathbf{0} \end{aligned}$$

Weighted prediction

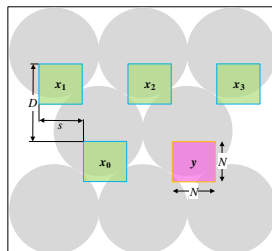


$$y' = w_0 x_0 + w_1 x_1 + w_2 x_2 + w_3 x_3$$

PU size is  $16 \times 16$



PU size is  $4 \times 4$  or  $8 \times 8$



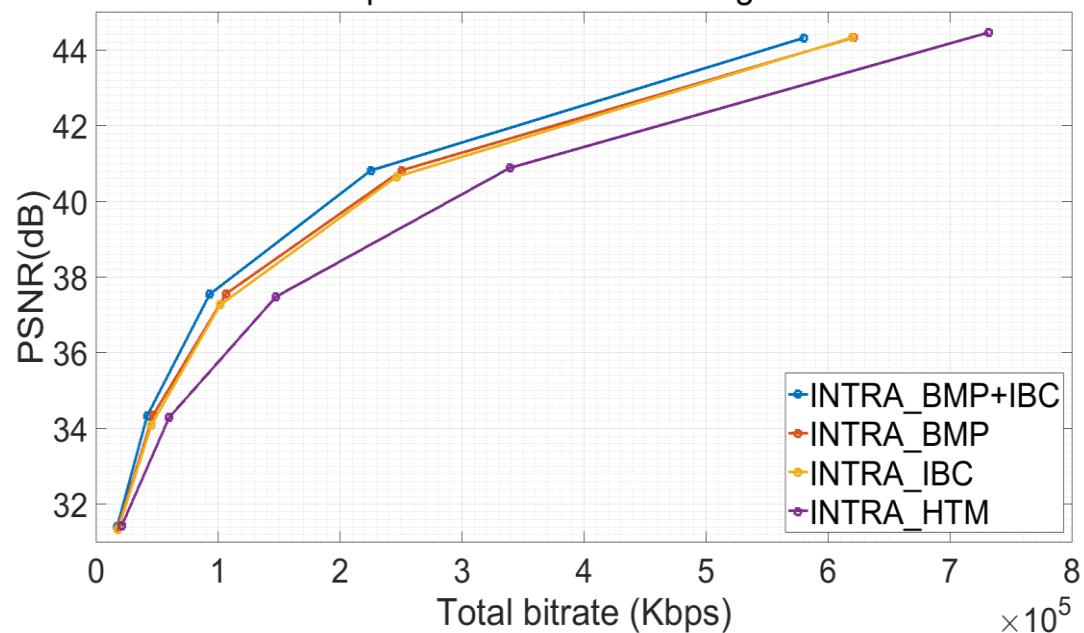
# M46261: Boundary matching based prediction



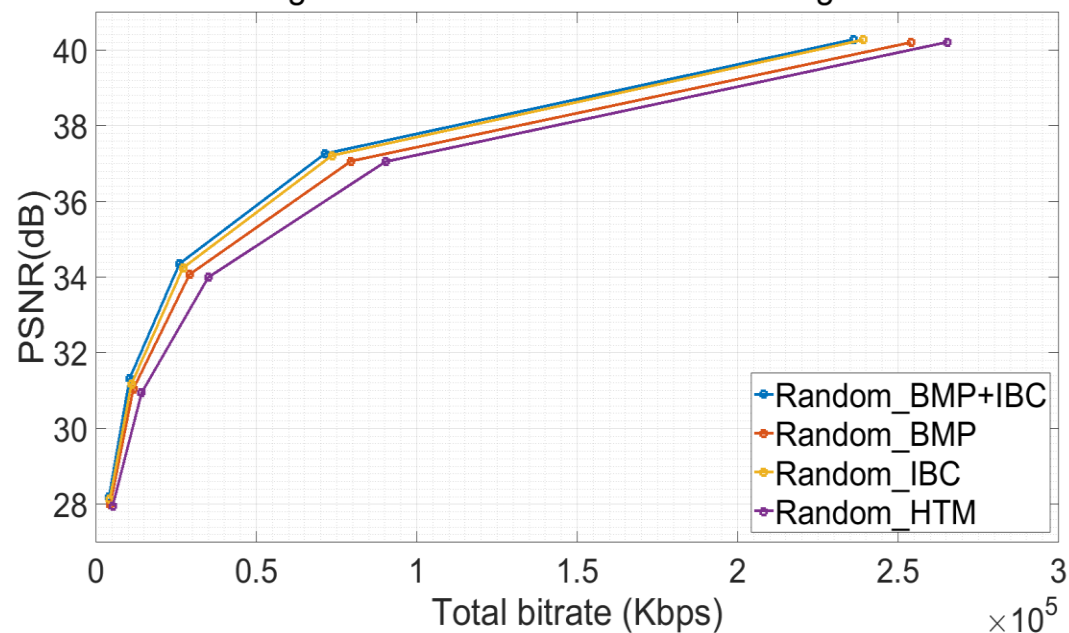
## Test Conditions

- Test sequences: Teapots, Mini-garden
- Total frames: 60 frames
- Resolution: 8656(H)  $\times$  6074(V)
- Anchor: HTM-HM mode
- Compared methods: IBC, BMP, IBC+BMP
- Configuration: all intra, random access
- QP: 24, 30, 36, 42 and 48
- Evaluation: RD curve and BD-Bitrate

Teapots under all intra configuration



Mini-garden under random access configuration







# Compression Performance on Plenoptic 1.0

BD-Bitrate result for QP 30, 36, 42 and 48 under the all Intra configuration

	IBC vs. HTM	BMP vs. HTM	IBC+BMP vs. HTM	IBC+BMP vs. IBC	Codec version
Toys	-16.44%	-21.17%	-23.33%	-8.20%	HM15.0+RExt
Trees	-3.69%	-4.14%	-5.36%	-1.74%	-8.0+SCM-2.0
<b>Avg.</b>	<b>-10.07%</b>	<b>-12.66%</b>	<b>-14.35%</b>	<b>-4.97%</b>	
Teapots	-22.28%	-24.78%	-32.55%	-13.21%	HM-
Mini-garden	-30.30%	-31.98%	-38.30%	-11.54%	16.9_SCM_8.0
<b>Avg.</b>	<b>-26.29%</b>	<b>-28.38%</b>	<b>-35.43%</b>	<b>-12.38%</b>	
<b>Avg. (All)</b>	<b>-18.18%</b>	<b>-20.52%</b>	<b>-24.89%</b>	<b>-8.67%</b>	

BD-Bitrate result for QP 30, 36, 42 and 48 under the random access configuration

	IBC vs. HTM	BMP vs. HTM	IBC+BMP vs. HTM	IBC+BMP vs. IBC	Codec version
Toys	-16.62%	-19.25%	-22.36%	-6.84%	HM-15.0+RExt-
Trees	-35.58%	-1.50%	-36.03%	-0.72%	8.0+SCM-2.0
<b>Avg.</b>	<b>-26.10%</b>	<b>-10.38%</b>	<b>-29.20%</b>	<b>-3.78%</b>	
Teapots	-21.76%	-11.93%	-27.16%	-6.78%	HM-
Mini-garden	-26.52%	-18.20%	-32.26%	-7.72%	16.9_SCM_8.0
<b>Avg.</b>	<b>-24.14%</b>	<b>-15.07%</b>	<b>-29.71%</b>	<b>-7.25%</b>	
<b>Avg. (All)</b>	<b>-25.12%</b>	<b>-12.72%</b>	<b>-29.45%</b>	<b>-5.52%</b>	

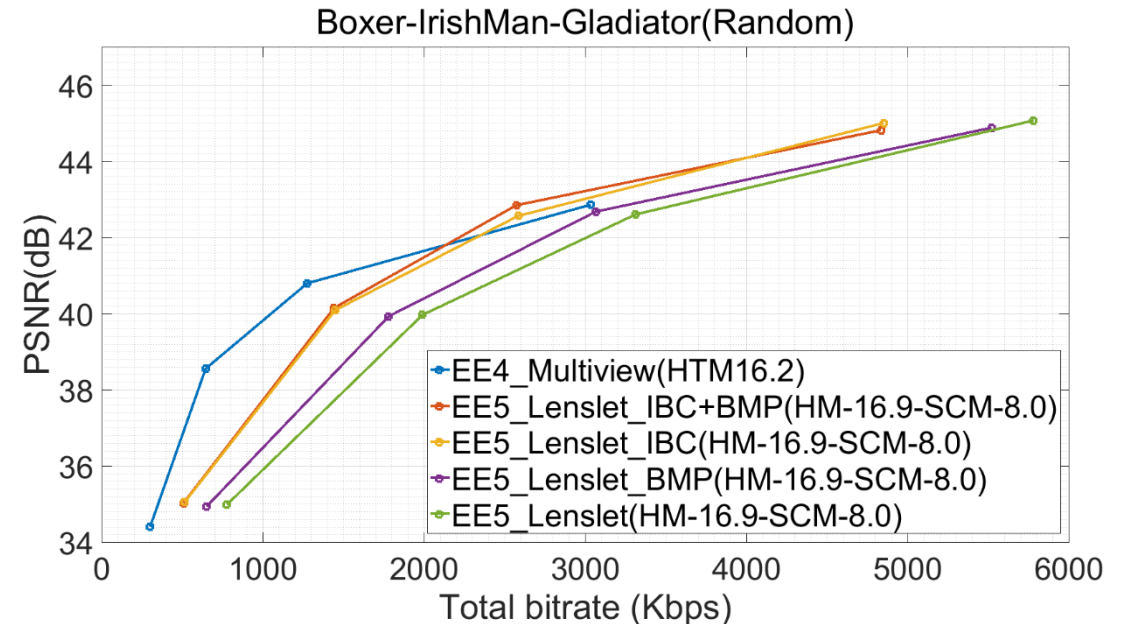
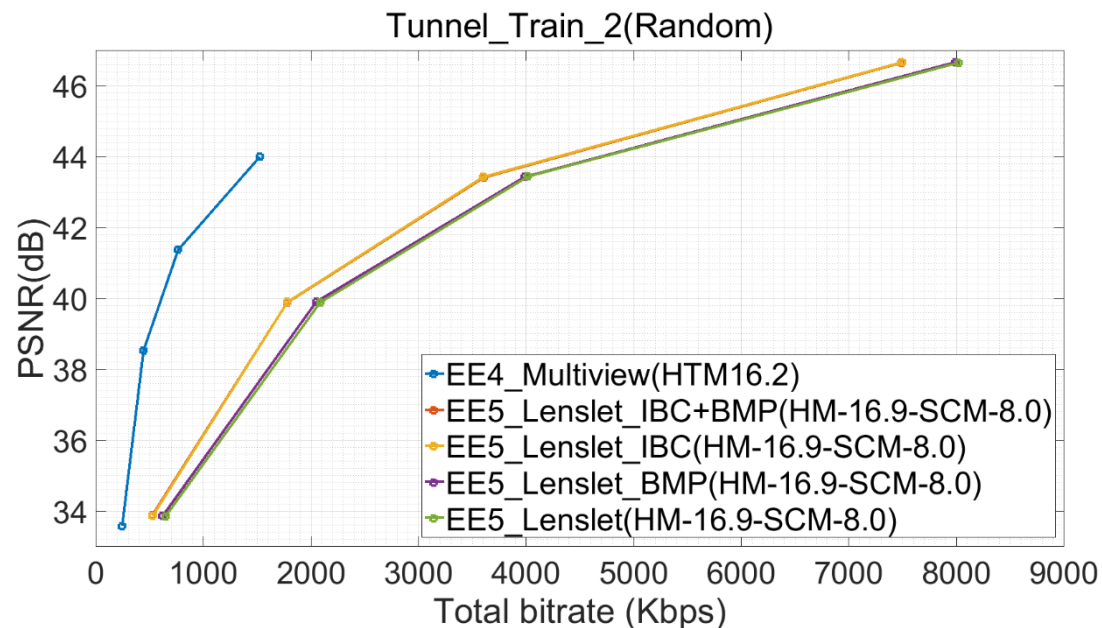
# Compression Performance on Plenoptic 2.0



## Test Conditions:

- Test sequences: Tunnel\_Train\_2, Chess-Pieces, Boxer-IrishMan-Gladiator and ChessPieces-MovingCamera.
- Total frames: 100 frames
- Resolution: R5:2048(H) × 2048(V), R8:3840 (H) × 2160(V),

- Anchor: HTM-HM mode
- Compared methods: IBC, BMP, IBC+BMP
- Configuration: all intra, random access
- QP: 28, 33, 38 and 46
- Evaluation: BD-Bitrate and RD curve



# Compression Performance on Plenoptic 2.0



BD-Bitrate result for QP 28,33,38 and 46 under all intra configuration

	IBC vs. HTM	BMP vs. HTM	IBC+BMP vs. HTM	IBC+BMP vs. IBC	Codec version
Tunnel_Train_2	-16.15%	-3.61%	-16.54%	-0.52%	
Chess-Pieces	-42.99%	-20.77%	-43.42%	-0.85%	
Boxer-IrishMan- Gladiator	-37.84%	-15.95%	-38.55%	-1.17%	HM- 16.9+SCM
ChessPieces- MovingCamera	-24.81%	-22.83%	-29.57%	-6.54%	-8.0
<b>Avg. (All)</b>	<b>-30.45%</b>	<b>-15.79%</b>	<b>-32.02%</b>	<b>-2.27%</b>	

BD-Bitrate result for QP 28,33,38 and 46 under random access configuration

	IBC vs. HTM	BMP vs. HTM	IBC+BMP vs. HTM	IBC+BMP vs. IBC	Codec version
Tunnel_Train_2	-13.66%	-2.01%	-13.63%	0.03%	
Chess-Pieces	-30.22%	-13.89%	-30.67%	-0.63%	
Boxer-IrishMan- Gladiator	-27.45%	-10.02%	-29.24%	-2.16%	HM- 16.9+SCM
ChessPieces- MovingCamera	-17.29%	-13.60%	-19.22%	-2.41%	-8.0
<b>Avg. (All)</b>	<b>-22.16%</b>	<b>-9.88%</b>	<b>-23.19%</b>	<b>-1.29%</b>	

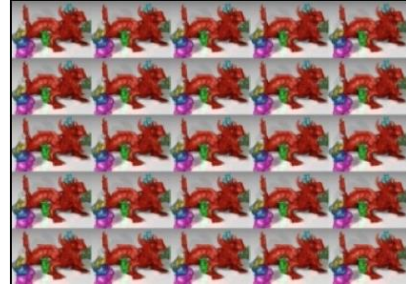
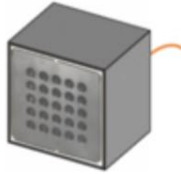


# Light Field Capture to Display System



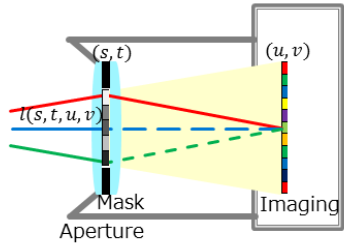
ViewPLUS  
ProFUSION 25

Multi-view  
camera

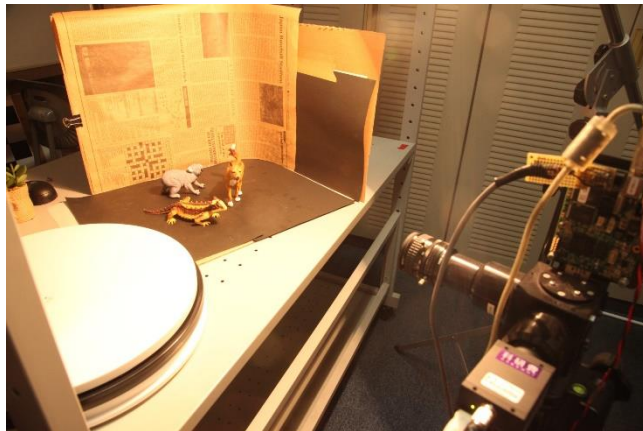


Acquired images

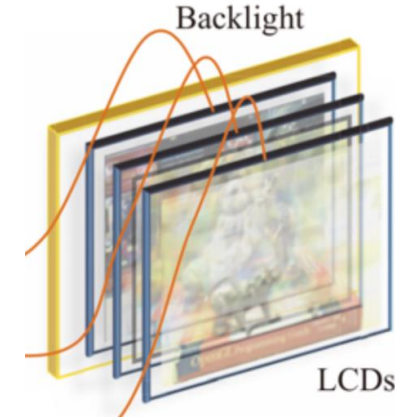
Coded Aperture Camera



Acquired images



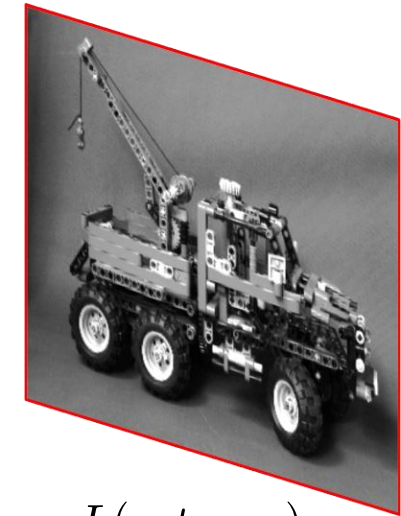
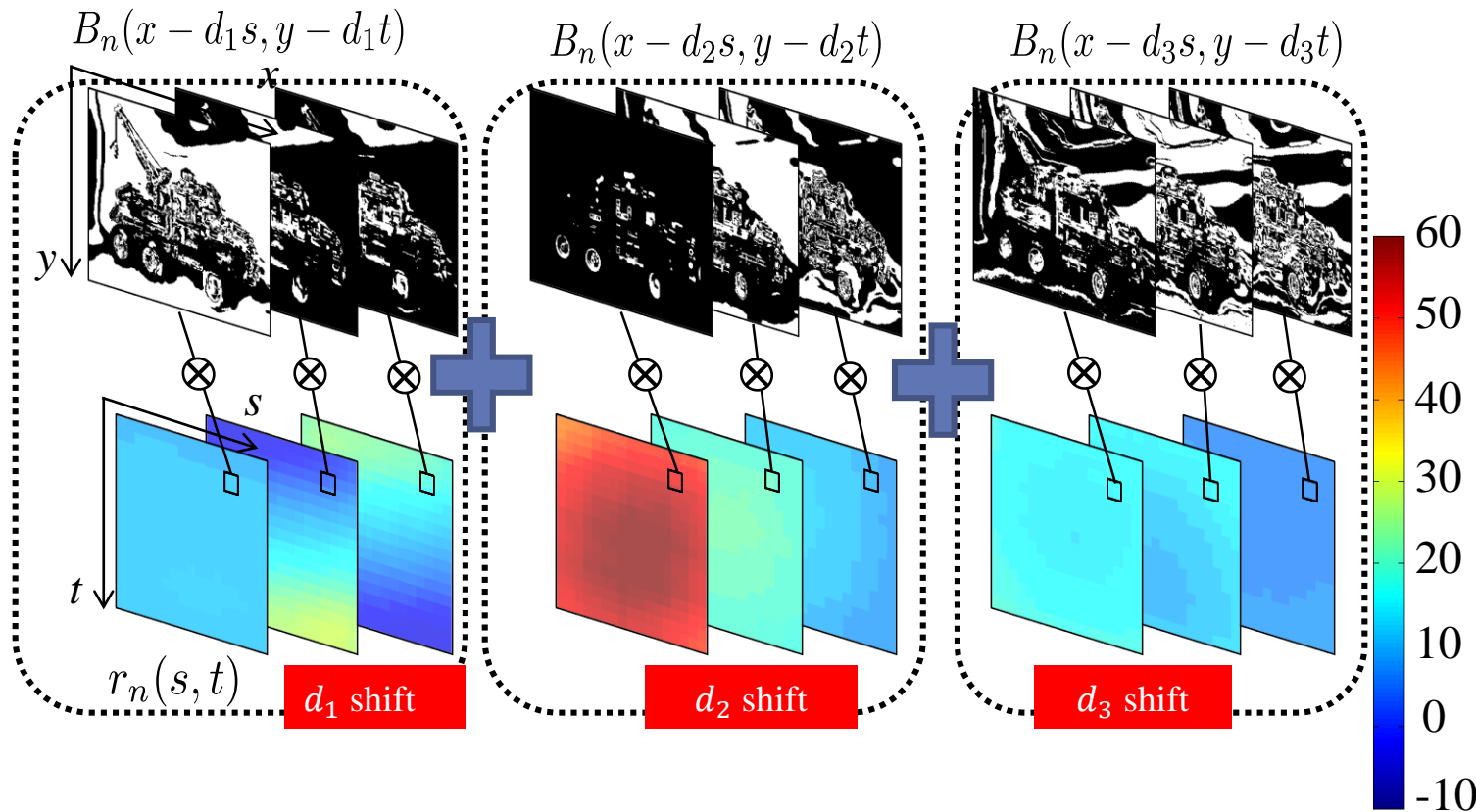
Layered patterns



Layer type 3D display

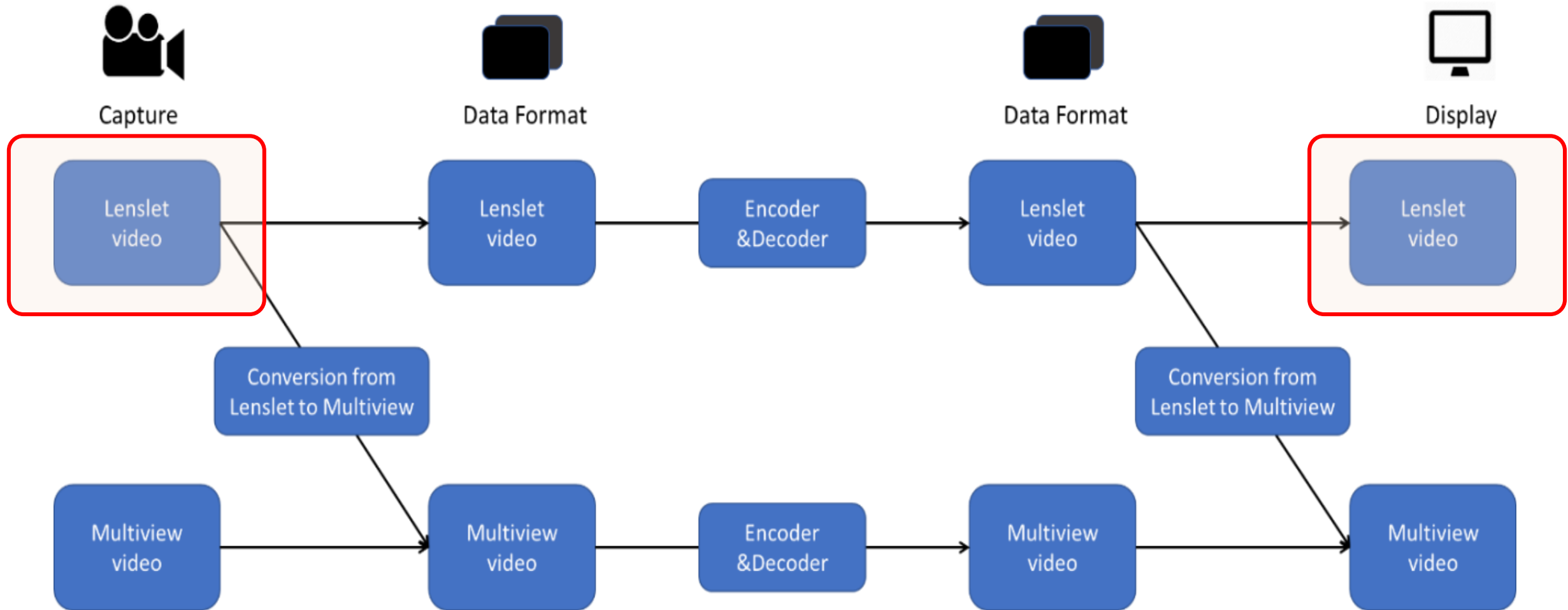


# Light Field Representation based on Weighted Sum of Binary Patterns



$L(s, t, x, y)$

# End-to-end system for dense light field





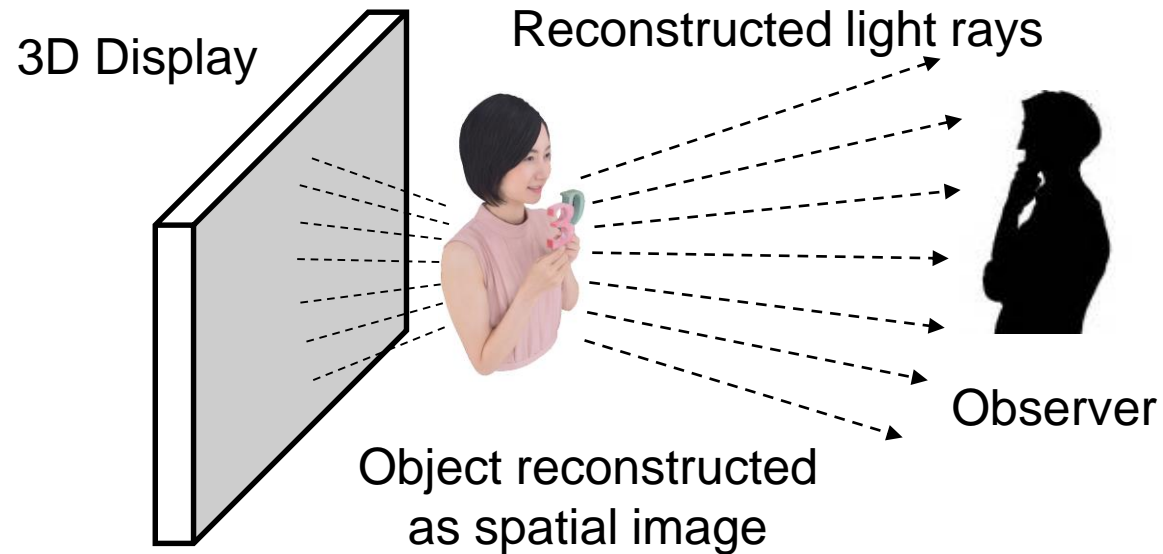
# 3D TV Based on Spatial Imaging

## Requirements for 3D TV

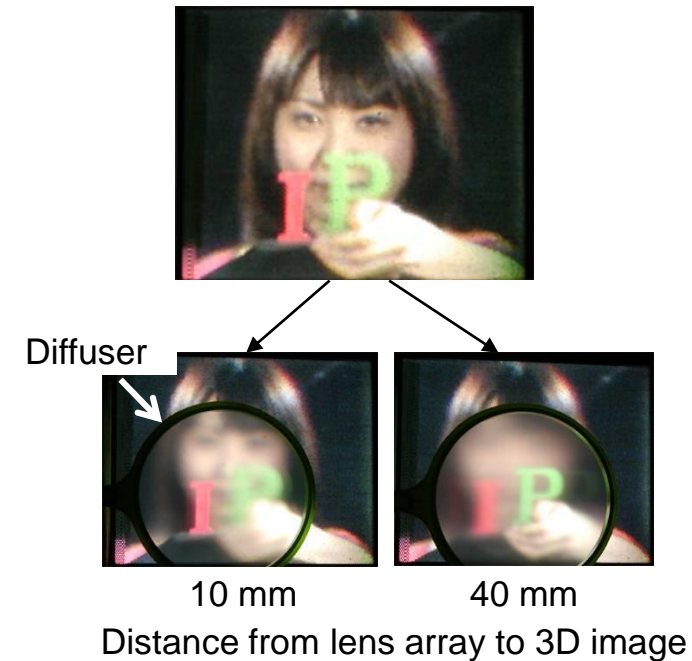
- No special glasses
- Full parallax
- Natural 3D image



## Spatial Imaging



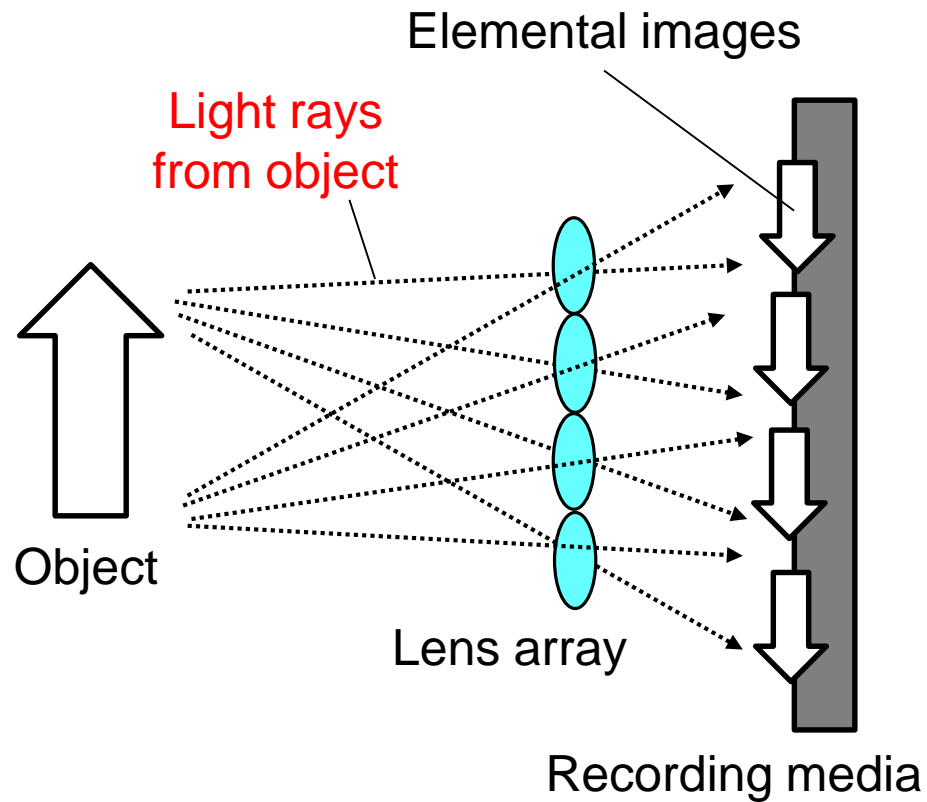
## 3D image based on Integral Photography



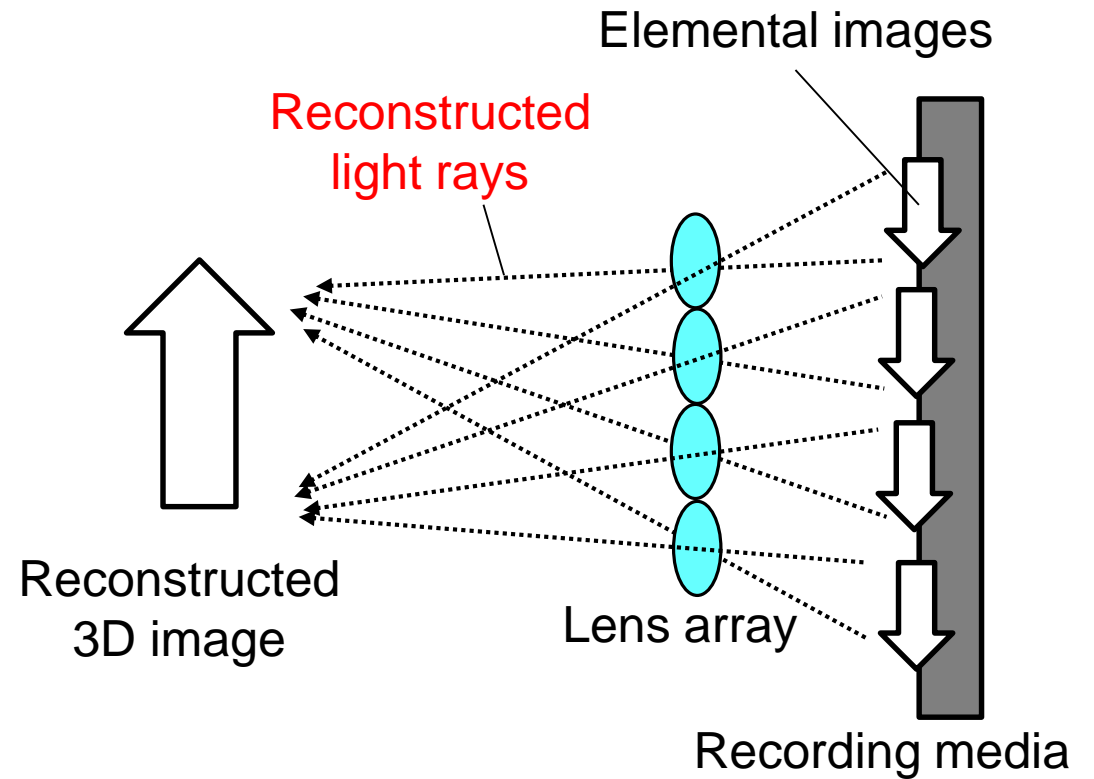
# Integral photography

## Basic principle

### Recording



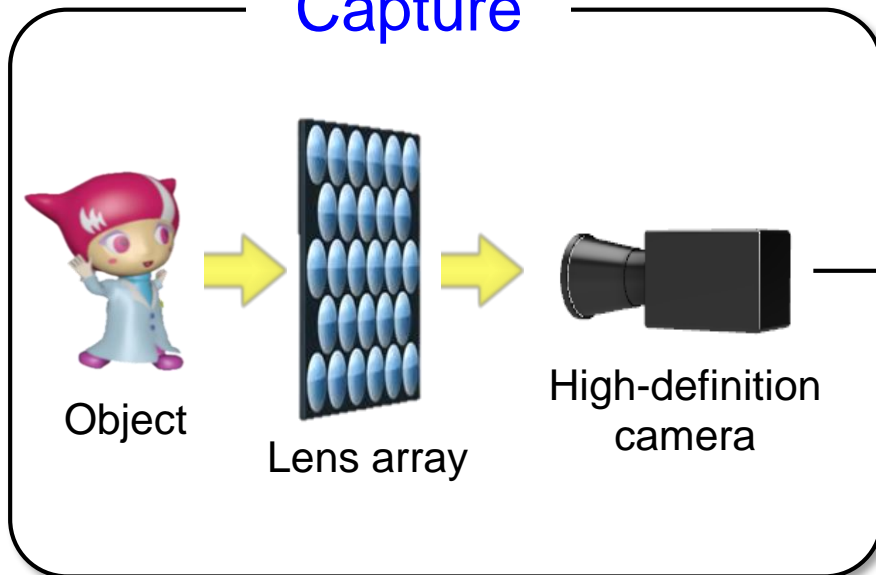
### Reconstructing



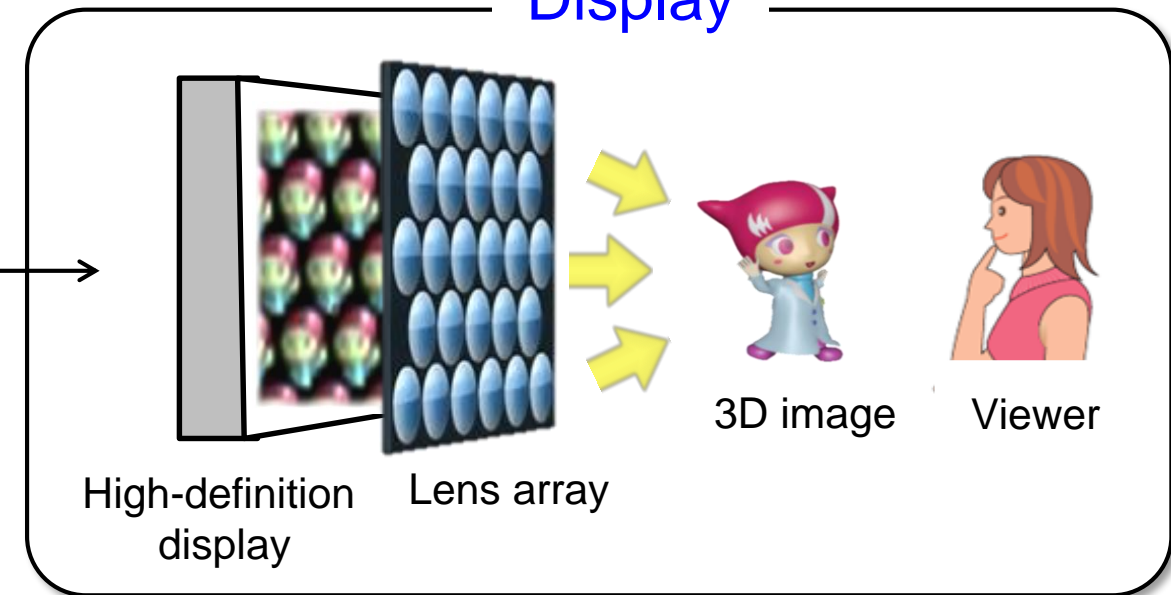
# Integral 3D TV

## Basic configuration

### Capture



### Display

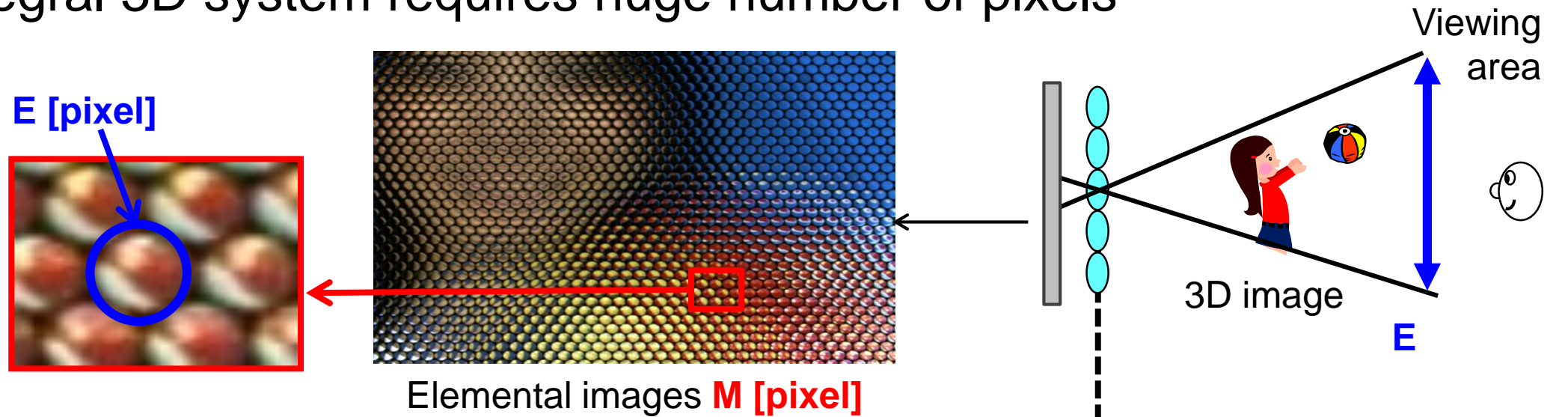


- Features
- Real-time capture and display of moving 3D images
  - Real objects (not computer graphics) are captured and displayed
  - Full-parallax images
- Problem
- Integral 3D system requires huge number of pixels



# Problem with Integral 3D system

- Integral 3D system requires huge number of pixels

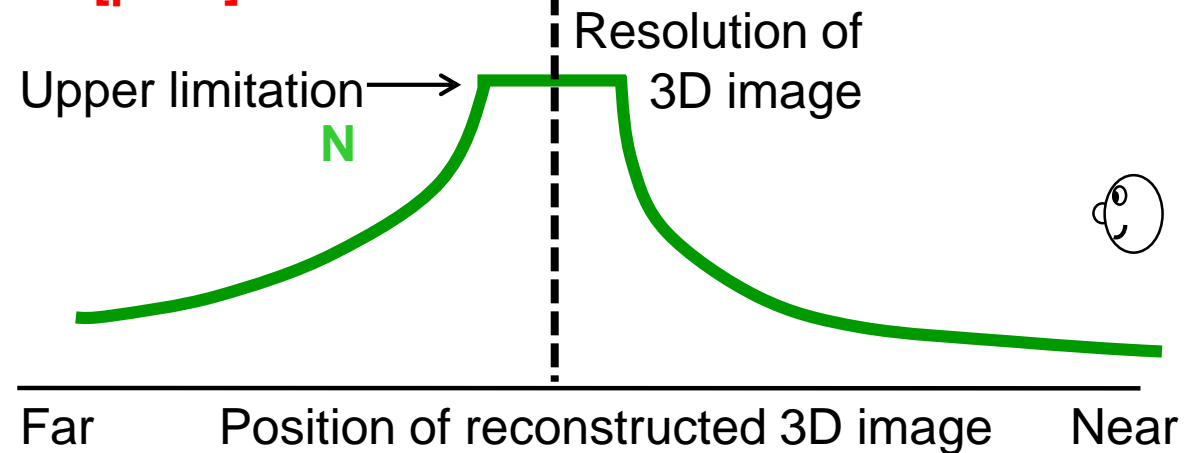


$$M = N \times E$$

**M**: Total pixels in elemental images

**E**: Number of pixels in one elemental image

**N**: Number of elemental images (lenses)



# Concluding Remark

- Lenslet data
  - integral display, 3D modeling, refocusing , multiview rendering.
  - Multimedia, medical applications
- Compression efficiency of lenslet data
  - Utilize the structure of lenslet data for inter/intra predictions
  - Novel image transform and entropy coding methods
  - Utilize machine learning tools
- New compression method for lenslet
  - leads to improvement over the existing standards.

# Acknowledgement



清華大學  
Tsinghua University

